KIRKLAND CERTIFICATE CONCERNING DESIGN AND CONSTRUCTION OF ELECTRONIC^{MUNICIPAL} COURT SPEED MEASURING DEVICES

I, Patricia Hernandez, do certify under penalty of the laws of the State of Washington that the following is true and correct:

I have been employed as a technician by American Traffic Solutions for 1 year. I became a speed validation technician on January 12, 2023 and have over 100 hours performing speed validation tests. I am nationally certified as a RADAR and LIDAR operator. The City of Kirkland currently uses the AutoPatrolTM 3D radar fixed speed safety camera system, an electronic speed measuring device provided through a contract with American Traffic Solutions, Inc. ("ATS"). Part of my duties include monitoring regular testing of the AutoPatrol 3D radar fixed speed safety camera systems used by the City of Kirkland.

ATS contracted with the City of Kirkland to provide an Automated Speed Enforcement ("ASE") system designed to record the speed of a vehicle and obtain photographs or other recorded images of the vehicle and the vehicle's registration plate while the vehicle is traveling in excess of speed limits in certain safety zones within posted limits.

The ASE program includes the use of the AutoPatrol 3D radar fixed speed safety camera systems at the following locations within the City of Kirkland:

Location Code	Location Description	Lanes Monitored
KRKF001	NB 132ND AVE NE @ MUIR ELEMENTARY/KAMIAKIN MIDDLE	1
KRKF002	SB 132ND AVE NE @ MUIR ELEMENTARY/KAMIAKIN MIDDLE	1
KRKF003	EB 80TH ST @ ROSE HILL ELEMENTARY	1
KRKF004	WB 80TH ST @ ROSE HILL ELEMENTARY	1
KRKF005	SB 724 STATE ST @ LAKEVIEW ELEMENTARY SCHOOL	1
KRKF006	WB 10600 NE 68TH ST @ LAKEVIEW ELEMENTARY SCHOOL	1
KRKF007	NB 12637 84TH AVE NE @ SANDBURG ES / FINN HILL MS / THOREAU ES	1
KRKF008	SB 14006 84TH AVE NE @ SANDBURG ES / FINN HILL MS / THOREAU ES	1

The AutoPatrol 3D radar fixed speed safety camera system operates by measuring vehicle speed, as well as position relative to the radar to calculate and differentiate multiple vehicles in the radar beam. The speed of a moving vehicle is measured by Doppler radar. Doppler radar is a generally accepted technology used for measuring speed. The AutoPatrol 3D radar technology is used throughout the US and Europe as well as other countries and is approved by the Swiss national metrology institute- METAS.

The AutoPatrol 3D radar fixed speed safety camera system uses a tracking radar sensor for measuring vehicle speeds and detecting speed violations. The AutoPatrol 3D radar is aligned at a fixed angle across the road. The AutoPatrol 3D radar emits a horizontal beam over the road surface as represented by the illustration below. The tracking radar can simultaneously detect multiple vehicles and measure their speed, distance, angle and movement within the radar beam. The radar tracks multiple vehicles by reconstructing vehicle movement from the measured object speed, angle and distance values. If a vehicle passes a defined trigger line, the radar

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outputs the vehicle's speed and lane information. The camera connected to the tracking radar uses this information to determine if there is a speed violation and to capture photographs showing the measured speed and lane on the databar of the captured images.



The tracking radar utilizes the Doppler Effect for speed determination. If an electromagnetic wave is emitted at a moving object, then the wave is reflected back from the moving object. The frequency of the wave received back by the radar shifts based on the speed of the moving object and its direction of travel. The tracking radar continuously determines this frequency shift of each object to calculate the object's speed. The tracking radar consists of two receiving antennas integrated into a single radar sensor. This configuration allows the radar to measure the distance and angle of the vehicle relative to the position of the radar sensor. Illustration A and B show the measurement principle in simplified form. The radar sensor emits a radar beam (illustration A). The radar beam is reflected by the vehicle (illustration B). The two receivers receive the reflected radar beam. The radar sensor evaluates the return frequency, as well as the phase difference of the reflected radar beam from both of the receivers. With the aid of these values the radar sensor calculates the vehicle position.



Prior to operation each day, the system performs a system self-test. This self-test performs an electronic tuning fork test to produce a specific frequency and returns an associated speed value. Only if the return value meets the acceptance criteria to show that the system is operating correctly will the system enter measure mode. Unless a self-test is successful, the system will not enter measure mode and no violations will be captured. Additional information stored as metadata within each image includes coordinates of the vehicle position at the time of capture. This information is extracted and utilized through a secondary speed verification process to provide yet another means to validate offender speed and position based on the two images obtained and image analytics. In addition to the internal system checks and the manufacturer calibration certification, the 3D radar system is subject to routine and independent calibration check of the speeds produced by the system at least annually by a qualified technician.

Each day the computer which controls the fixed speed safety camera system is rebooted. The reboot is initiated each day and each time the computer is rebooted an internal check is performed on all operations of

each fixed speed safety camera system, including the clocks, sensors, camera and speed calculating hardware and software, in order to verify that all operations are functioning correctly. When the internal check detects a problem with one of the operations on a given fixed speed safety camera system, then that particular fixed speed safety camera system is inactivated and a request for service is relayed to ATS support personnel. This means that violations cannot be issued until any internal problem is fixed.

Speed validation tests are regularly performed on each installed and operable AutoPatrol 3D radar fixed speed safety camera system. The test is conducted by having a LIDAR Operator obtain true measurements of up to five vehicles per lane in the ascending and/or descending direction. The speed of the vehicle is captured by the LIDAR Operator and then relayed via cellular to an ATS Technician. The ATS Technician then compares the vehicle speed measured by the AutoPatrol 3D radar fixed speed safety camera system to the speed measured by the LIDAR Operator to ensure the accuracy of the AutoPatrol 3D radar fixed speed safety camera system. ATS maintains the results of each test in a Validation Report. The speed validation for each system was performed on the following date and the systems at each location were found to be in proper working order:

Location	Location Description		
Code			
KRKF001	NB 132ND AVE NE @ MUIR ELEMENTARY/KAMIAKIN MIDDLE	2/13/2024	
KRKF002	SB 132ND AVE NE @ MUIR ELEMENTARY/KAMIAKIN MIDDLE	2/13/2024	
KRKF003	EB 80TH ST @ ROSE HILL ELEMENTARY	2/1/2024	
KRKF004	WB 80TH ST @ ROSE HILL ELEMENTARY	2/1/2024	
KRKF005	SB 724 STATE ST @ LAKEVIEW ELEMENTARY SCHOOL	2/13/2024	
KRKF006	WB 10600 NE 68TH ST @ LAKEVIEW ELEMENTARY SCHOOL	2/13/2024	
KRKF007	NB 12637 84TH AVE NE @ SANDBURG ES / FINN HILL MS / THOREAU ES	2/8/2024	
KRKF008	SB 14006 84TH AVE NE @ SANDBURG ES / FINN HILL MS / THOREAU ES	2/13/2024	

Preventative maintenance, including visual inspections, is regularly performed on the AutoPatrol 3D radar fixed speed safety camera systems. Preventative maintenance activities include: cleaning of the cameras and housing, general site inspection of environment and road conditions, inspection of poles, bases and enclosures, and inspection of system cables and connections. The location and date that preventative maintenance is performed is recorded in the Preventative Maintenance Log, which along with the Validation Report(s) referenced above, is attached hereto.

I am a custodian, or otherwise qualified witness, as to the attached records. I make this declaration based on personal knowledge, and if called and sworn as a witness, I could and would testify as set forth in the following paragraph.

Attached as Exhibits are: Exhibit A - Speed Validation Reports, Exhibit B - Preventative Maintenance Logs, and Exhibit C - Annual System Verification Certificate for all AutoPatrol 3D radar fixed speed safety camera systems installed and used by the City of Kirkland. All documents and materials included as Exhibit A, Exhibit B and Exhibit C are authentic and are what they purport to be, and accurately describe the matters set forth therein. All such records are business records in that they are: (1) records kept in the ordinary course of business; (2) created at or near the time of the transactions or events reflected therein by, or based on information from, a person with knowledge of the transaction or events; and (3) kept as part of a regular business activity.

Based upon my education, training, experience, and knowledge of the AutoPatrol 3D radar fixed speed safety camera system, it is my opinion that the system is so designed and constructed as to accurately employ measurement techniques based on a division of distance over time in such a manner that it will give accurate measurements of the speed of motor vehicles.

I, Patricia Hernandez, certify (or declare) under penalty of perjury under the laws of the State of Washington that the foregoing is true and correct.

Dated this 6th day of March 2024 in Mesa, AZ

Patricia Hernandez

Patricia Hernandez, Speed Validation Technician



Speed Validation Report Client: Kirkland, WA

Validation Date: February 1, 2024

- KRKF003 EB 80TH ST @ ROSE HILL ELEMENTARY
 Radar Serial Number: 590-113/64176
- KRKF004 WB 80TH ST @ ROSE HILL ELEMENTARY
 - o Radar Serial Number: 590-112/62298

Validation Date: February 8, 2024

KRKF007 – NB 12637 84TH AVE NE @ SANDBURG ES / FINN HILL MS / THOREAU ES
 Radar Serial Number: 590-113/68421

Validation Date: February 13, 2024

- KRKF001 NB 132ND AVE NE @ MUIR ELEMENTARY/KAMIAKIN MIDDLE
 - o Radar Serial Number: 590-112/61693
- KRKF002 SB 132ND AVE NE @ MUIR ELEMENTARY/KAMIAKIN MIDDLE
 - o Radar Serial Number: 590-113/61513
- KRKF005 SB 724 STATE ST @ LAKEVIEW ELEMENTARY SCHOOL
 - o Radar Serial Number: 590-113/68392
- KRKF006 WB 10600 NE 68TH ST @ LAKEVIEW ELEMENTARY SCHOOL
 - o Radar Serial Number: 590-113/68391
- KRKF008 SB 14006 84TH AVE NE @ SANDBURG ES / FINN HILL MS / THOREAU ES
 - o Radar Serial Number: 590-113/68429

Equipment:

Pro-Lite Plus Hand held Lidar Serial Number: LP05509

Certification Date: October 27, 2023

Lidar Operator: Charles Goodrich

RLC Operator: Catherine Koselka-Thompson

RLC Operator: Katherine Vasquez

RLC Operator: Patricia Hernandez

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KIRKLAND MUNICIPAL COURT



A speed validation test was conducted for the sites listed above. The Lidar Operator, obtained true measurements of five vehicles per lane in the ascending and/or descending direction. Those speeds were obtained using a Kustom Signals Pro-Lite+ hand held Lidar instrument. The speed of the vehicle is captured by the Lidar Operator and then relayed via cellular to the RLC Technician. The RLC Technician is monitoring the vehicle speed at the Fixed Speed Camera system simultaneously to ensure the accuracy of the system. The speed validation tests performed on the above-listed dates confirmed the accuracy of the Fixed Speed Camera systems at each location.

I, Patricia Hernandez, certify that the information contained in this report is true and accurate.

Signed: <u>Patricia Hernandez</u>

Date: March 6, 2024 Mesa, Arizona American Traffic Solutions Speed Integrity Team



Certificate of A	chievement
Speed Integrity Has successfully completed the 16 P Speed Integrity Technic	<i>Technician</i> hour course for cian
This course encompasses all the necessary tasks required to per Technician. Through this course each participant is required to d written and practical examinations. In addition, this course certifi	arform the duties as a Speed Integrity lisplay the proper competency through ies each participants as a Lidar operator.
Presented to: Charles Goodrich	
This Day: March 29, 2016	-AM
ATS American Traffic Solutions	Matthew Gioia Police Traffic Laser/Radar Instructor
ROLD Celtificate di Aches-Imeril. V1.0 American Traffic Solutiona, Inc., 7681 East Gray I	Road, Scottedale, AZ 85262 October 2 ROLD-0113-CH0-01

Certificate of A	Achievement
Speed Integrity Has successfully completed the court	ty <i>Technician</i> rse for Speed Inegrity Technician
This course encompasses all the necessary tasks required Through this course each participant is required to display Technology. In addition, this course certifies each participa	to perform the duties as a Speed Integrity Technician. the proper competencies in Radar and Laser nts as a Radar and Lidar operator.
Presented to: Catherine Kosel	ka
This Day: August 21st, 2019	Tel You
American Traffic Solutions*	Tylor Yochim Radar Instructor
RDLD Certificate of Achievement V1.0 American Traffic Solutions, Inc., 7681 East	st Gray Road, Scottsdare, AZ 85250 Centificate # VCC-0821-AZ-02



Certificate of A	chievement
Speed Integrity Has successfully completed the course	Technician
This course encompasses all the necessary tasks required to Through this course each participant is required to display the Technology. In addition, this course certifies each participants	perform the duties as a Speed Integrity Technician. proper competencies in Radar and Laser as a Lidar operator.
Katherine Vasque	
This Day: August 10, 2021	
American Traffic Solutions	Tylor Yochim Radar Instructor
RDLD Certificate of Adhievement V1 0 American Traffic Solutions, Inc., 7681 East Ge	ay Road, Scottsdale, AZ 85260 Centificate # VCC-1022-AZ-03

Certificate of A	chievement
Speed Integrity 3 Has successfully completed the course for	Technician or Speed Inegrity Technician
This course encompasses all the necessary tasks required to per Through this course each participant is required to display the p Technology. In addition, this course certifies each participants as	erform the duties as a Speed Integrity Technician. roper competencies in Radar and Laser s a Lidar operator.
Presented to: Patricia Hernandez	
This Day: January 12, 2023	
	Type Yot
American Traffic Solutions	Tylor Yochim Radar Instructor
RDLD Certificate of Achievement, V1.0 American Traffic Solutions, Inc., 7581 East Gray I	Road, Scottsdale, AZ 85260 Centricate # VCG-1022-AZ-07



	PB Electronics	Inc.
248	W Peaceful Ct., Shephere	dsville, KY 40165
Factory Authorized C	Sold 543-7032 WWW.pbell	ectronics.com er MPH Kustom Decatur and LTL
ration y ration 200 c	Carbon Control for Owner	in the the test of the books and bit
	Certificate of Cal	ibration
Manufacturar Kustam	Martal, Para L Va	Carial Mumbers D05500
manundsturer, Rustoni	model: Pro-Lite	Serial Number: LP00003
ereby certify that this Spee eration under my supervisio	d Measuring Device has been on. This Speed Measuring De	checked for accuracy and correctness of vice is certified accurately within +/- 0.5 mp
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Tunin Received action of the second stationary mode using equi the laser transmitter of this de evices as established by the CC License number PG-18- Rectory Arthenized Service Bester Art PH Discident Service Service Service Control of the service Service Service Service Control of the service Service Service Service Control of the service Service Service Service Control of the service C	d Measuring Device has been on. This Speed Measuring De pment traceable to National In evice has been tested and four Pederal Communications Cor 12552 Technician Sig	checked for accuracy and correctness of vice is certified accurately within +/- 0.5 mp stitute of Standards and technology. and to be within specified range for Laser mmission and IACP gnature





SELF-ACCURACY TEST Kustom Signals Pro-Lite+ Lidar Speed Measurement Tool

DATE: _____ February 1, 2024_____

Start of shift "Self-Diagnostic test" time: _____ 11:17 AM_____

Start of shift Distance check: _____100'_____lidar

End of shift "Self-Diagnostic test" time: _____ 11:54 AM_____

End of shift Distance check: 100'

City and State:___Kirkland, WA____

Lidar Serial Number: LP05509

Certification Date: October 27th, 2023

OPERATOR: _____Charles Goodrich_____

I, *Charles Goodrich*, certify that the Kustom Signals Pro-Lite+ Lidar speed measurement device was setup, tested, and operated in accordance with the manufactures specifications to include its selfdiagnostic check.

Further, I certified that the self-check distance was completed and accurate.

Signature: Con M Date: February 1, 2024





SELF-ACCURACY TEST Kustom Signals Pro-Lite+ Lidar Speed Measurement Tool

DATE: _____ February 8, 2024_____

Start of shift "Self-Diagnostic test" time: _____ 12:37 PM_____

Start of shift Distance check: ____100'____lidar

End of shift "Self-Diagnostic test" time: _____ 12:52 PM_____

End of shift Distance check: 100'

City and State: ___Kirkland, WA____

Lidar Serial Number: LP05509

Certification Date: _____October 27th, 2023_____

OPERATOR: Charles Goodrich

I, *Charles Goodrich*, certify that the Kustom Signals Pro-Lite+ Lidar speed measurement device was setup, tested, and operated in accordance with the manufactures specifications to include its selfdiagnostic check.

Further, I certified that the self-check distance was completed and accurate.

Signature: Com M Date: February 8, 2024





SELF-ACCURACY TEST Kustom Signals Pro-Lite+ Lidar Speed Measurement Tool

DATE: _____ February 13, 2024_____

Start of shift "Self-Diagnostic test" time: _____ 11:59 AM_____

Start of shift Distance check: _____100'_____lidar

End of shift "Self-Diagnostic test" time: _____ 12:48 PM_____

End of shift Distance check: 100'

City and State: ___Kirkland, WA____

Lidar Serial Number:_____LP05509_____

Certification Date: October 27th, 2023

OPERATOR: Charles Goodrich

I, *Charles Goodrich*, certify that the Kustom Signals Pro-Lite+ Lidar speed measurement device was setup, tested, and operated in accordance with the manufactures specifications to include its selfdiagnostic check.

Further, I certified that the self-check distance was completed and accurate.

Signature: Com Man Date: February 13, 2024





Date			2/13/2024			
Time			12:23 PM			
Site ID			KRKF001			
Location			Kirkland, WA			
			NB 132ND AVE NE @ MUIR ELEMENTARY/KAMIAKIN			
Address			MIDDLE			
Posted Speed Limit				20MP	Н	
Trigger Speed Limit				26MPI	Н	
Speed Type				Schoo	bl	
Lidar Technie	cian			Charles Go	odrich	
AutoPatrol To	AutoPatrol Technician			Catherine Thompson		
Lidar Serial N	lumber		LP05509			
Radar Serial	Number		590-112/61693			
Detection Ty	pe		Autopatrol-Radar			
Measure Mod	le Capture	TRANSFER	Yes			
Photo enforc	ement signs	s present	Yes			
Pass/ Fail			Pass			
Ascending o	r Descendin	g	Descending			
City Lane	Times	Lidar Speeds	AP Speeds	Delta	Comments	
1	12.23.51	26	27	1	Market Ballens A.	
1	12.24.27	24	24	0		
1	12.25.23	19	18	-1		
1	12.25.27	15	14	-1		
1	12.26.29	27	28	1		





Date			2/13/2024		
Time			12:21 PM		
Site ID			KRKF002		
Location			Kirkland, WA		
			SB 132ND AVE NE @ MUIR ELEMENTARY/KAMIAKIN		
Address			MIDDLE		
Posted Spee	d Limit			20MP	Н
Trigger Spee	d Limit			26MP	Н
Speed Type				Schoo	ol
Lidar Technic	cian			Charles Go	odrich
AutoPatrol To	echnician		Catherine Thompson		
Lidar Serial N	lumber		LP05509		
Radar Serial	Number		590-113/61513		
Detection Ty	pe		Autopatrol-Radar		
Measure Mod	le Capture		Yes		
Photo enforc	ement signs	s present	Yes		
Pass/ Fail			Pass		
Ascending of	r Descendin	g	Descending		
City Lane	Times	Lidar Speeds	AP Speeds	Delta	Comments
1	12.21.09	26	26	0	
1	12.21.19	30	29	-1	
1	12.21.48	24	24	0	
1	12.21.53	30	30	0	
1 12.22.01 28			29 1		





Date			2/1/2024		
Time			11:22 AM		
Site ID			KRKF003		
Location			Kirkland, WA		
Address			EB 80TH ST @ ROSE HILL ELEMENTARY		
Posted Spee	d Limit		20MPH		
Trigger Spee	d Limit			26MPI	4
Speed Type				Schoo	bl
Lidar Technic	cian			Charles Go	odrich
AutoPatrol Te	echnician		C	atherine Th	ompson
Lidar Serial N	lumber		LP05509		
Radar Serial	Number		590-113/64176		
Detection Ty	ре	2000 N	Autopatrol-Radar		
Measure Mod	le Capture			Yes	
Photo enforcement signs present			Yes		
Pass/ Fail		See Speak	Pass		
Ascending or Descending			Descend	ling	
City Lane	Times	Lidar Speeds	AP Speeds	Delta	Comments
1	11.22.21	30	30	0	
1	11.22.51	26	26	0	
1	11.22.55	27	26	-1	
1	11.23.39	22	22	0	
1	11.24.38	29	28 -1		





Date			2/1/2024			
Time			11:47 AM			
Site ID			KRKF004			
Location			Kirkland, WA			
Address			WB 80TH ST @ ROSE HILL ELEMENTARY			
Posted Spee	Posted Speed Limit			20MPH		
Trigger Spee	d Limit			26MPI	4	
Speed Type				Schoo	bl	
Lidar Technic	cian			Charles Go	odrich	
AutoPatrol Te	echnician			Patricia Heri	nandez	
Lidar Serial N	lumber		LP05509			
Radar Serial	Number		590-112/62298			
Detection Ty	pe		Autopatrol-Radar			
Measure Mod	le Capture		Yes			
Photo enforc	hoto enforcement signs present			Yes		
Pass/ Fail			Pass			
Ascending of	Descendin	g	Descending			
City Lane	Times	Lidar Speeds	AP Speeds	Delta	Comments	
1	11.47.07	28	28	0		
1	11.47.46	26	26	0		
1	11.48.29	25	24	-1		
1	11.48.46	25	25	0		
1	11.49.08	24	24	0		





Date			2/13/2024		
Time			12:43 PM		
Site ID			KRKF005		
Location			Kirkland, WA		
Address			SB 724 STATE ST @ LAKEVIEW ELEMENTARY		
Address Postad Speed Limit					
Trigger Speed Limit				26MPH	4
Speed Type				Schoo	
Lidar Technic	cian			Charles Go	odrich
AutoPatrol Te	echnician		Catherine Thompson		
Lidar Serial N	lumber		LP05509		
Radar Serial	Number		590-113/68392		
Detection Ty	ре		Autopatrol-Radar		
Measure Mod	le Capture		Yes		
Photo enforc	ement signs	s present	Yes		
Pass/ Fail		and the second s	Pass		
Ascending of	r Descendin	g	Descending		
City Lane	Times	Lidar Speeds	AP Speeds	Delta	Comments
1	12.43.17	34	34	0	
1	12.43.20	31	32	1	
1	12.43.30	22	22	0	
1	12.43.37	20	19	-1	
1	12.43.40	20	19 -1		





Date				2/13/20)24	
Time				12:39	PM	
Site ID				12:39 PM KRKF006 Kirkland, WA 600 NE 68TH ST @ LAKEVIEW ELEMENTAR SCHOOL 20MPH 26MPH School Charles Goodrich Charles Goodrich LP05509 590-113/68391 Autopatrol-Radar		
Location				Kirkland	,WA	
			WB 10600 NE 68	BTH ST @ LA	KEVIEW ELEMENTARY	
Address				SCHO	DL	
Posted Spee	d Limit			20MP	Н	
Trigger Spee	d Limit		26MPH			
Speed Type			School			
Lidar Technic	cian		Charles Goodrich			
AutoPatrol Technician			Catherine Thompson			
Lidar Serial N	lumber		LP05509			
Radar Serial Number			590-113/68391			
Detection Type			Autopatrol-Radar			
Measure Mode Capture				Yes	c.	
Photo enforc	ement signs	s present		Yes		
Pass/ Fail				Pass	3	
Ascending or	r Descendin	g		Descen	ding	
City Lane	Times	Lidar Speeds	AP Speeds	Delta	Comments	
1	12.39.17	15	16	1		
1	12.39.46	27	28	1		
1	12.40.11	24	25	1		
1	12.41.17	27	28	1		
1	12.41.24	31	32	1		





Date				2/8/20	/8/2024			
Time		Section of the	12:42 PM					
Site ID				KRKF	007			
Location				Kirkland	d, WA			
Address			NB 12637 84TH HI	I AVE NE @) SANDBURG ES / FINN OREAU ES			
Posted Spee	d Limit			20M	РΗ			
Trigger Spee	d Limit		26MPH					
Speed Type			School					
Lidar Technician			Charles Goodrich					
AutoPatrol Technician			Katherine Vasquez					
Lidar Serial Number			LP05509					
Radar Serial Number			590-113/68421					
Detection Type				Autopatro	ol-Radar			
Measure Mode Capture				Yes	\$			
Photo enforcement signs present				Yes	S			
Pass/ Fail				Pas	S			
Ascending o	r Descendin	g		Descer	nding			
City Lane	Times	Lidar Speeds	AP Speeds	Delta	Comments			
1	12.42.46	24	25	1				
1	12.42.57	21	21	0				
1	12.44.27	32	32	0				
1	12.46.20	30	30	0				
1	12.47.32	21	21	0				





Date			2/13/2024				
Time			12:04 PM				
Site ID				KRKFO	008		
Location				Kirkland	,WA		
Address			SB 14006 84TH AVE NE @ SANDBURG ES / FINN HILL MS / THOREAU ES				
Posted Spee	d Limit			20MP	H		
Trigger Spee	d Limit		26MPH				
Speed Type			School				
Lidar Technie	cian		Charles Goodrich				
AutoPatrol Technician			Catherine Thompson				
Lidar Serial Number			LP05509				
Radar Serial Number				590-113/6	68429		
Detection Type				Autopatrol	-Radar		
Measure Mode Capture				Yes			
Photo enforcement signs present				Yes			
Pass/ Fail				Pass	6		
Ascending o	r Descendin	g		Descene	ding		
City Lane	Times	Lidar Speeds	AP Speeds	Delta	Comments		
1	12.04.02	28	28	0			
1	12.05.23	25	25	0			
1	12.06.26	21	21	0	Carbon March		
1	12.06.44	32	33	1			
1	12.06.46	31	31	0	The states		



Report No .: 1910-071EA-264

Revision:

N/C

Radar Sensor Calibration Verification Certificate of Calibration

FILED MAR 1 3 2024

MUNICIPAL COURT

Model: RRS24F-ST3

Part Number / Serial Number: 590-112/61693 Ex. 590-XXX / 6XXXX

Description: **Radar Characteristics Validation** In compliance with: RRS24F-ST3 Radar Sensor Calibration Verification Procedure Documentation (5030-0150)

> Date of Issue: October 27, 2023

Owner of EUT:

Verra Mobility 1150 N. Alma School Rd Mesa, AZ 85201

Attention of:

Engineering Department Phone: (480) 443-7000

Test Facility		
Test Laboratory	Keystone Compliance, LLC	
Address	131 North Columbus Innerbelt	
City, State, Zip Code	New Castle, PA 16101	
Phone	(724) 657-9940	
Email	emcteam@keystonecompliance.com	
Web Site	www.keystonecompliance.com	

Test Personnel				
Name	Camren Morgan			
Title	EMC Test Engineer			
Signature	Erren drugen			

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1910-071EA-264 Report No.:

Revision:

N/C

Radar Sensor Calibration Verification Certificate of Calibration

Model: RRS24F-ST3

Part Number / Serial Number: 590-112/61693 Ex. 590-XXX / 6XXXX

Date of Issue: October 27, 2023

The frequency measurements performed and recorded within this report demonstrate that the JENOPTIK RR24F-ST3 radar has an accuracy of less than or equal to 0.62 mph in the range of 6.21 mph to 62.14 mph and an accuracy of 0.62 mph to 1.86 mph in the range of 62.14 mph to 186.41 mph. This is equal to or better than +/- 1 mph accuracy up to 100 mph, as specified by the manufacturer.

FSK Frequency Set 1							
Nominal Frequency (GHz)	Measured Frequency (GHz)	Amplitude (dBm)	Frequency Deviation (MHz)	Limit (MHz)	Results		
$f_0 = 24.08$	24.076325	16.1408327	-3.67	+/- 48.2	PASS		
f ₁ = 24.08725	24.083474	16.6384424	-3.78	+/- 48.2	PASS		
$f_2 = 24.089$	24.085424	17.8610734	-3.58	+/- 48.2	PASS		
$f_3 = 24.09$	24.086401	17.923438	-3.60	+/- 48.2	PASS		

FSK Frequency Set 2							
Nominal Frequency (GHz)	Measured Frequency (GHz)	Amplitude (dBm)	Frequency Deviation (MHz)	Limit (MHz)	Results		
$f_0 = 24.12$	24.117926	16.3312441	-2.07	+/- 48.2	PASS		
f ₁ = 24.12725	24.125401	16.3428575	-1.85	+/- 48.2	PASS		
$f_2 = 24.129$	24.127025	17.3314865	-1.98	+/- 48.2	PASS		
f ₃ = 24.13	24.128	17.3848474	-2.00	+/- 48.2	PASS		

FSK Frequency Set 3							
Nominal Frequency (GHz)	Measured Frequency (GHz)	Amplitude (dBm)	Frequency Deviation (MHz)	Limit (MHz)	Results		
$f_0 = 24.16$	24.15855	15.8376406	-1.45	+/- 48.2	PASS		
f ₁ = 24.16725	24.165702	16.2942417	-1.55	+/- 48.2	PASS		
$f_2 = 24.169$	24.167651	17.6538716	-1.35	+/- 48.2	PASS		
$f_3 = 24.17$	24.168626	17.780231	-1.37	+/- 48.2	PASS		

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Report No .: 1910-071EA-220

Revision:

N/C

Radar Sensor Calibration Verification Certificate of Calibration

MAR 1 3 2024

KIRKLAND MUNICIPAL COURT

FILED

Model: RRS24F-ST3

Part Number / Serial Number: 590-113/61513 Ex. 590-XXX / 6XXXX

Description:

Radar Characteristics Validation In compliance with: RRS24F-ST3 Radar Sensor Calibration Verification Procedure Documentation (5030-0150)

Date of Issue: June 19, 2023

Owner of EUT:

Verra Mobility 1150 N. Alma School Rd Mesa, AZ 85201

Attention of:

Engineering Department Phone: (480) 443-7000

Test Facility				
Test Laboratory	Keystone Compliance, LLC			
Address	131 North Columbus Innerbelt			
City, State, Zip Code	New Castle, PA 16101			
Phone	(724) 657-9940			
Email	emcteam@keystonecompliance.com			
Web Site	www.keystonecompliance.com			

Test Personnel				
Name	Camren Morgan			
Title	EMC Test Engineer			
Signature	Enn drug			

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Report No.: 1910-071EA-220

Revision:

N/C

Radar Sensor Calibration Verification Certificate of Calibration

Model: RRS24F-ST3

Part Number / Serial Number: 590-113/61513 Ex. 590-XXX / 6XXXX

Date of Issue: June 19, 2023

The frequency measurements performed and recorded within this report demonstrate that the JENOPTIK RR24F-ST3 radar has an accuracy of less than or equal to 0.62 mph in the range of 6.21 mph to 62.14 mph and an accuracy of 0.62 mph to 1.86 mph in the range of 62.14 mph to 186.41 mph. This is equal to or better than +/- 1 mph accuracy up to 100 mph, as specified by the manufacturer.

FSK Frequency Set 1							
Nominal Frequency (GHz)	Measured Frequency (GHz)	Amplitude (dBm)	Frequency Deviation (MHz)	Limit (MHz)	Results		
$f_0 = 24.08$	24.077951	1.07583065	-2.05	+/- 48.2	PASS		
f ₁ = 24.08725	24.085101	0.4834434	-2.15	+/- 48.2	PASS		
f ₂ = 24.089	24.08705	1.82907643	-1.95	+/- 48.2	PASS		
f ₃ = 24.09	24.088025	1.807434	-1.98	+/- 48.2	PASS		

FSK Frequency Set 2							
Nominal Frequency (GHz)	Measured Frequency (GHz)	Amplitude (dBm)	Frequency Deviation (MHz)	Limit (MHz)	Results		
$f_0 = 24.12$	24.118575	5.82124907	-1.43	+/- 48.2	PASS		
$f_1 = 24.12725$	24.125725	5.14385949	-1.53	+/- 48.2	PASS		
$f_2 = 24.129$	24.127676	5.90749047	-1.32	+/- 48.2	PASS		
$f_3 = 24.13$	24.128651	5.66284744	-1.35	+/- 48.2	PASS		

FSK Frequency Set 3					
Nominal Frequency (GHz)	Measured Frequency (GHz)	Amplitude (dBm)	Frequency Deviation (MHz)	Limit (MHz)	Results
$f_0 = 24.16$	24.158226	4.4716356	-1.77	+/- 48.2	PASS
$f_1 = 24.16725$	24.165376	5.84224569	-1.87	+/- 48.2	PASS
$f_2 = 24.169$	24.167326	6.93187163	-1.67	+/- 48.2	PASS
$f_3 = 24.17$	24.168301	7.18223101	-1.70	+/- 48.2	PASS

CONTROLLED DATA Properietary and Confidential Page 16



VERRA MOBILITY V A MOBILITY V A MOBILITY V A MOBILITY			
Date & Time: 02/24/2024 15:56:00 Site ID: KRKF001 Location: NB 132ND AVE NE @ MUIR ELEMENTARY/KAMIAKIN MIDDLE			
Product: AutoPatrol Technician Name: Thomas Yuen		See Associated Ticket:	
Item	Status	Note/Action (If Status N/A, please specify)	
1. Clean dirt, grime, and graffiti off enclosure and glass.			
1.1. Clean Graffiti. Check physical integrity. Check paint/housing for graffiti and (or) other vandalism.	N/A		
1.2. Clean Glass:			
Clean and inspect all glass and enclosures.			
1.3. Clean Enclosure (Interior):			
Clear vents/fans of obstruction. Remove dust and dirt by vacuum/wiping.			
1.4. Check Enclosure:			
If enclosure moved during cleaning, tighten base.			
2. Perform a general site inspection to include environmental and road conditions.			
2.1. PLP/Loop Loop:			
Check for exposed or cut loop wiring, and epoxy wear and tear.			
2.2. Power & Grounding:			
Inspect all power and grounding connections.			
2.3. Radar:			
Inspect radar and cables. Visually inspect antenna.			
2.4. WVDs:			
Check for popped out pucks, visible cracks, or other noticeable damage.			
3. Inspect poles, bases, and enclosures.			

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3.1. Pole: Check sturdiness. Check hurricane collar and confirm screws are tight.	N/A	
3.2. Base: Check for cracks. Ensure bolts (and latch bolt) are tight and secure inside base.	N/A	
3.3. Enclosure: Confirm straps are tight and secure against pole. Tighten if loose.	N/A	
4. Inspect cables and connections.		
4.1. Cables: Check all cables for visible wear or damage.	N/A	
4.2. Connections: Check for exposed wires on pole connecting to radar, camera enclosure, and strobe.	N/A	

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5.2. Pole:



5.1. Enclosure:

5.3. Photo Enforcement Sign(s):



FILED MAR 1 3 2024

V A VERRA V A MOBILITY V A MOBILITY	MUNICIPAL COURT PREVENTIVE MAINTENANCE CHECKLIST				
Date & Time: 02/24/2024 15:47:00 Site ID: KRKF002 Location: SB 132ND AVE NE @ MUIR ELEMENTARY/KAMIAKIN MIDDLE					
Product: AutoPatrol Technician Name: 1	lomas Yuen	See Associated Ticket:			
Item	Statu	s Note/	Action (If Status N/A, plea	se specify)	
1. Clean dirt, grime, and graffiti off enclosure and glass.					
1.1. Clean Graffiti. Check physical integrity. Check paint/housing for graffiti and (or) other vandalism.	N/A				
1.2. Clean Glass: Clean and inspect all glass and enclosures.	Pass				
1.3. Clean Enclosure (Interior): Clear vents/fans of obstruction. Remove dust and dirt by vacuum/wiping.	N/A				
1.4. Check Enclosure: If enclosure moved during cleaning, tighten base.	N/A				
 Perform a general site inspection to include environmental and road conditions. 					the states
2.1. PLP/Loop Loop: Check for exposed or cut loop wiring, and epoxy wear and tear.					
2.2. Power & Grounding: Inspect all power and grounding connections.	N/A				
2.3. Radar: Inspect radar and cables. Visually inspect antenna.	N/A				
2.4. WVDs: Check for popped out pucks, visible cracks, or other noticeable damage.					
3. Inspect poles, bases, and enclosures.					
			100000		

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3.1. Pole: Check sturdiness. Check hurricane collar and confirm screws are tight.	N/A	
3.2. Base: Check for cracks. Ensure bolts (and latch bolt) are tight and secure inside base.	N/A	
3.3. Enclosure: Confirm straps are tight and secure against pole. Tighten if loose.	N/A	
4. Inspect cables and connections.		
4.1. Cables: Check all cables for visible wear or damage.	N/A	
4.2. Connections: Check for exposed wires on pole connecting to radar, camera enclosure, and strobe.	N/A	

5. Take (and attach) photo of enclosure, pole, and photo enforcement sign(s) for presence and damage.

5.1. Enclosure:



5.2. Pole:





5.3. Photo Enforcement Sign(s):