## CERTIFICATE CONCERNING DESIGN AND CONSTRUCTION OF ELECTRONIC SPEED MEASURING DEVICES

I, Lesieli Casale, do certify under penalty of the laws of the State of Washington that the following is true and correct:

I have been employed as a technician by American Traffic Solutions for 2 years. I became a speed validation technician on January 12, 2023 and have over 100 hours performing speed validation tests. I am nationally certified as a RADAR and LIDAR operator. The City of Kirkland currently uses the AutoPatrol<sup>TM</sup> 3D radar fixed speed safety camera system, an electronic speed measuring device provided through a contract with American Traffic Solutions, Inc. ("ATS"). Part of my duties include monitoring regular testing of the AutoPatrol 3D radar fixed speed safety camera systems used by the City of Kirkland.

ATS contracted with the City of Kirkland to provide an Automated Speed Enforcement ("ASE") system designed to record the speed of a vehicle and obtain photographs or other recorded images of the vehicle and the vehicle's registration plate while the vehicle is traveling in excess of speed limits in certain safety zones within posted limits.

The ASE program includes the use of the AutoPatrol 3D radar fixed speed safety camera systems at the following locations within the City of Kirkland:

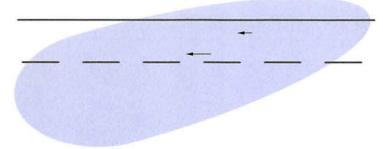
Location Code	Location Description	Lanes Monitored
KRKF001	NB 132ND AVE NE @ MUIR ELEMENTARY/KAMIAKIN MIDDLE	1
KRKF002	SB 132ND AVE NE @ MUIR ELEMENTARY/KAMIAKIN MIDDLE	1
KRKF003	EB 80TH ST @ ROSE HILL ELEMENTARY	1
KRKF004	WB 80TH ST @ ROSE HILL ELEMENTARY	1
KRKF005	SB 724 STATE ST @ LAKEVIEW ELEMENTARY SCHOOL	1
KRKF006	WB 10600 NE 68TH ST @ LAKEVIEW ELEMENTARY SCHOOL	1
KRKF007	NB 12637 84TH AVE NE @ SANDBURG ES / FINN HILL MS / THOREAU ES	1
KRKF008	SB 14006 84TH AVE NE @ SANDBURG ES / FINN HILL MS / THOREAU ES	1

The AutoPatrol 3D radar fixed speed safety camera system operates by measuring vehicle speed, as well as position relative to the radar to calculate and differentiate multiple vehicles in the radar beam. The speed of a moving vehicle is measured by Doppler radar. Doppler radar is a generally accepted technology used for measuring speed. The AutoPatrol 3D radar technology is used throughout the US and Europe as well as other countries and is approved by the Swiss national metrology institute- METAS.

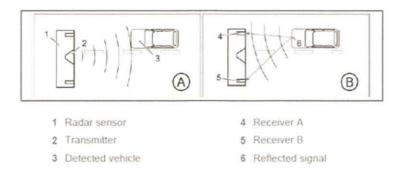
The AutoPatrol 3D radar fixed speed safety camera system uses a tracking radar sensor for measuring vehicle speeds and detecting speed violations. The AutoPatrol 3D radar is aligned at a fixed angle across the road. The AutoPatrol 3D radar emits a horizontal beam over the road surface as represented by the illustration below. The tracking radar can simultaneously detect multiple vehicles and measure their speed, distance, angle and movement within the radar beam. The radar tracks multiple vehicles by reconstructing vehicle movement from the measured object speed, angle and distance values. If a vehicle passes a defined trigger line, the radar

1

outputs the vehicle's speed and lane information. The camera connected to the tracking radar uses this information to determine if there is a speed violation and to capture photographs showing the measured speed and lane on the databar of the captured images.



The tracking radar utilizes the Doppler Effect for speed determination. If an electromagnetic wave is emitted at a moving object, then the wave is reflected back from the moving object. The frequency of the wave received back by the radar shifts based on the speed of the moving object and its direction of travel. The tracking radar continuously determines this frequency shift of each object to calculate the object's speed. The tracking radar consists of two receiving antennas integrated into a single radar sensor. This configuration allows the radar to measure the distance and angle of the vehicle relative to the position of the radar sensor. Illustration A and B show the measurement principle in simplified form. The radar sensor emits a radar beam (illustration A). The radar sensor evaluates the return frequency, as well as the phase difference of the reflected radar beam from both of the receivers. With the aid of these values the radar sensor calculates the vehicle position.



Prior to operation each day, the system performs a system self-test. This self-test performs an electronic tuning fork test to produce a specific frequency and returns an associated speed value. Only if the return value meets the acceptance criteria to show that the system is operating correctly will the system enter measure mode. Unless a self-test is successful, the system will not enter measure mode and no violations will be captured. Additional information stored as metadata within each image includes coordinates of the vehicle position at the time of capture. This information is extracted and utilized through a secondary speed verification process to provide yet another means to validate offender speed and position based on the two images obtained and image analytics. In addition to the internal system checks and the manufacturer calibration certification, the 3D radar system is subject to routine and independent calibration check of the speeds produced by the system at least annually by a qualified technician.

Each day the computer which controls the fixed speed safety camera system is rebooted. The reboot is initiated each day and each time the computer is rebooted an internal check is performed on all operations of

each fixed speed safety camera system, including the clocks, sensors, camera and speed calculating hardware and software, in order to verify that all operations are functioning correctly. When the internal check detects a problem with one of the operations on a given fixed speed safety camera system, then that particular fixed speed safety camera system is inactivated and a request for service is relayed to ATS support personnel. This means that violations cannot be issued until any internal problem is fixed.

Speed validation tests are regularly performed on each installed and operable AutoPatrol 3D radar fixed speed safety camera system. The test is conducted by having a LIDAR Operator obtain true measurements of up to five vehicles per lane in the ascending and/or descending direction. The speed of the vehicle is captured by the LIDAR Operator and then relayed via cellular to an ATS Technician. The ATS Technician then compares the vehicle speed measured by the AutoPatrol 3D radar fixed speed safety camera system to the speed measured by the LIDAR Operator to ensure the accuracy of the AutoPatrol 3D radar fixed speed safety camera system. ATS maintains the results of each test in a Validation Report. The speed validation for each system was performed on the following date and the systems at each location were found to be in proper working order:

Location Code	Location Description	Date of Test
KRKF001	NB 132ND AVE NE @ MUIR ELEMENTARY/KAMIAKIN MIDDLE	10/12/2023
KRKF002	SB 132ND AVE NE @ MUIR ELEMENTARY/KAMIAKIN MIDDLE	10/12/2023
KRKF003	EB 80TH ST @ ROSE HILL ELEMENTARY	10/12/2023
KRKF004	WB 80TH ST @ ROSE HILL ELEMENTARY	10/12/2023
KRKF005	SB 724 STATE ST @ LAKEVIEW ELEMENTARY SCHOOL	10/12/2023
KRKF006	WB 10600 NE 68TH ST @ LAKEVIEW ELEMENTARY SCHOOL	10/12/2023
KRKF007	NB 12637 84TH AVE NE @ SANDBURG ES / FINN HILL MS / THOREAU ES	10/12/2023
KRKF008	SB 14006 84TH AVE NE @ SANDBURG ES / FINN HILL MS / THOREAU ES	10/12/2023

Preventative maintenance, including visual inspections, is regularly performed on the AutoPatrol 3D radar fixed speed safety camera systems. Preventative maintenance activities include: cleaning of the cameras and housing, general site inspection of environment and road conditions, inspection of poles, bases and enclosures, and inspection of system cables and connections. The location and date that preventative maintenance is performed is recorded in the Preventative Maintenance Log, which along with the Validation Report(s) referenced above, is attached hereto.

I am a custodian, or otherwise qualified witness, as to the attached records. I make this declaration based on personal knowledge, and if called and sworn as a witness, I could and would testify as set forth in the following paragraph.

Attached as Exhibits are: Exhibit A - Speed Validation Reports, Exhibit B - Preventative Maintenance Logs, and Exhibit C - Annual System Verification Certificate for all AutoPatrol 3D radar fixed speed safety camera systems installed and used by the City of Kirkland. All documents and materials included as Exhibit A, Exhibit B and Exhibit C are authentic and are what they purport to be, and accurately describe the matters set forth therein. All such records are business records in that they are: (1) records kept in the ordinary course of business; (2) created at or near the time of the transactions or events reflected therein by, or based on information from, a person with knowledge of the transaction or events; and (3) kept as part of a regular business activity.

Based upon my education, training, experience, and knowledge of the AutoPatrol 3D radar fixed speed safety camera system, it is my opinion that the system is so designed and constructed as to accurately employ measurement techniques based on a division of distance over time in such a manner that it will give accurate measurements of the speed of motor vehicles.

I, Lesieli Casale, certify (or declare) under penalty of perjury under the laws of the State of Washington that the foregoing is true and correct.

Dated this 9th day of November 2023 in Mesa, Arizona

Lesieli Casale

Lesieli Casale, Speed Validation Technician



## Speed Validation Report Client: Kirkland, WA

### Validation Date: October 12, 2023

- KRKF001 NB 132ND AVE NE @ MUIR ELEMENTARY/KAMIAKIN MIDDLE
  Radar Serial Number: 590-113/66806
- KRKF002 SB 132ND AVE NE @ MUIR ELEMENTARY/KAMIAKIN MIDDLE
  - o Radar Serial Number: 590-113/61513
- KRKF003 EB 80TH ST @ ROSE HILL ELEMENTARY
  - o Radar Serial Number: 590-113/64095
- KRKF004 WB 80TH ST @ ROSE HILL ELEMENTARY
  - o Radar Serial Number: 590-113/ 66135
- KRKF005 SB 724 STATE ST @ LAKEVIEW ELEMENTARY SCHOOL
  - o Radar Serial Number: 590-113/68392
- KRKF006 WB 10600 NE 68TH ST @ LAKEVIEW ELEMENTARY SCHOOL
  - o Radar Serial Number: 590-113/68391
- KRKF007 NB 12637 84TH AVE NE @ SANDBURG ES / FINN HILL MS / THOREAU ES
  Radar Serial Number: 590-113/68421
- KRKF008 SB 14006 84TH AVE NE @ SANDBURG ES / FINN HILL MS / THOREAU ES
  - o Radar Serial Number: 590-113/68429

#### Equipment:

.

Pro-Lite Plus Hand held Lidar Serial Number: LP05509 Certification Date: October 27, 2022 Lidar Operator: Charles Goodrich RLC Operator: Catherine Koselka-Thompson FILED NOV 1 5 2023

KIRKLAND MUNICIPAL COURT



A speed validation test was conducted for the sites listed above. The Lidar Operator, obtained true measurements of five vehicles per lane in the ascending and/or descending direction. Those speeds were obtained using a Kustom Signals Pro-Lite+ hand held Lidar instrument. The speed of the vehicle is captured by the Lidar Operator and then relayed via cellular to the RLC Technician. The RLC Technician is monitoring the vehicle speed at the Fixed Speed Camera system simultaneously to ensure the accuracy of the system. The speed validation tests performed on the above-listed dates confirmed the accuracy of the Fixed Speed Camera systems at each location.

I, Lesieli Casale, certify that the information contained in this report is true and accurate.

Lesieli Casale

Signed: \_\_\_\_\_ Date: November 9, 2023 Mesa, Arizona American Traffic Solutions Speed Integrity Team



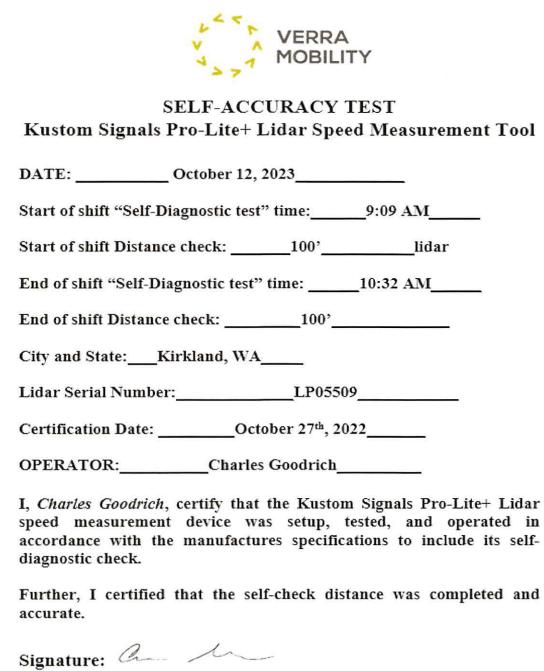
Certificate of A	Achievement
Speed Integrit Has successfully completed the Speed Integrity Tect	16 hour course for
This course encompasses all the necessary tasks required to Technician. Through this course each participant is required to written and practical examinations. In addition, this course ce	o display the proper competency through
Presented to: Charles Goodrich	
This Day: March 29, 2016	AN
ATS American Traffic Solutions	Matthew Gloia Police Traffic Laser/Radar Instructor
ROLD Contribute of Advancement VII.5 American Traffic Solutions, Inc., 7681 East 0	my Road, Scottadale, AZ: \$5560 Centificate # ROLD-0513-CH-01

Certificate of Ac	chievement
Speed Integrity To Has successfully completed the course for s	
This course encompasses all the necessary tasks required to perform Through this course each participant is required to display the prop Technology. In addition, this course certifies each participants as a	per competencies in Radar and Laser
Presented to: Catherine Koselka	
This Day: August 21st, 2019	
ROLD Certificate of Activevement, V1.9 American Traffic Solutions, Inc. 7681 East Gray Boa	Tylor Yochim Radar Instructor



	PB Electronics Inc. W Peaceful Ct., Shepherdsville 502 543-7032 <u>www.pbelectror</u> ed Calibration Center for Stalke	ics.com
	Certificate of Calibra	tion
Manufacturer: Kustom	Model: ProLite	Serial Number: LP05509
operation under my supervisio		certified accurately within +/- 0.5 mp
operation under my supervision in stationary mode using equi The laser transmitter of this de	÷	of Standards and technology.
operation under my supervision in stationary mode using equi The laser transmitter of this do Devices as established by the FCC License number PG-18-	on. This Speed Measuring Device is pment traceable to National Institute evice has been tested and found to a Federal Communications Commiss	o certified accurately within +/- 0.5 mp of Standards and technology. be within specified range for Laser sion and IACP.
operation under my supervision in stationary mode using equi The laser transmitter of this do Devices as established by the	on. This Speed Measuring Device is pment traceable to National Institute evice has been tested and found to a Federal Communications Commiss	o certified accurately within +/- 0.5 mp of Standards and technology. be within specified range for Laser sion and IACP.
operation under my supervision in stationary mode using equi The laser transmitter of this do Devices as established by the FCC License number PG-18- PB ELECTRONICS Factory Authorized	on. This Speed Measuring Device is pment traceable to National Institute evice has been tested and found to a Federal Communications Commiss	o certified accurately within +/- 0.5 mp of Standards and technology. be within specified range for Laser sion and IACP.





Date: October 12, 2023





Date	We get the			10/12/20	023
Time			9:48 AM		
Site ID			KRKF001		
Location			Ki	rkland, Was	
Location					LEMENTARY/KAMIAKIN
Address				MIDDL	
Posted Spee	ed Limit			20MP	Н
Trigger Spe	ed Limit			26MP	н
Speed Type				Schoo	bl
Lidar Techni	ician	Sec. 18 - 19		Charles Go	odrich
AutoPatrol T	echnician		Catherine Thompson		
Lidar Serial	Number		LP05509		
Radar Serial	Number		590-113/66806		
Detection T)	/pe		Autopatrol-Radar		
Measure Mode Capture				Yes	
Photo enforcement signs present				Yes	
Pass/ Fail				Pass	1
Ascending o	or Descend	ing		Descend	ling
City Lane	Times	Lidar Speeds	AP Speeds	Delta	Comments
1	09.48.04	17	18	1	10 10
1	09.48.10	22	21	-1	
1	09.48.20	20	20	0	
1	09.49.57	41	41	0	
1	09.50.12	24	24	0	





Date				10/12/20	23	
Time			9:51 AM			
Site ID				KRKF0	02	
Location				Kirkland,	WA	
			SB 132ND AVE	NE @ MUIR EI	LEMENTARY/KAMIAKIN	
Address				MIDDL	E	
Posted Spee	ed Limit			20MP	Н	
Trigger Spe	ed Limit			26MP	Н	
Speed Type				Schoo	bl	
Lidar Techn	ician			Charles Go	odrich	
AutoPatrol T	echnician		Catherine Thompson			
Lidar Serial	Number		LP05509			
Radar Serial	Number		590-113/61513			
Detection Ty	/pe		Autopatrol-Radar			
Measure Mo	de Captur	e		Yes	Yes	
Photo enfor	noto enforcement signs present			Yes		
Pass/ Fail	10 M M		Pass			
Ascending o	or Descend	ing		Descend	ling	
City Lane	Times	Lidar Speeds	AP Speeds	Delta	Comments	
1	09.51.33	29	29	0		
1	09.52.09	28	28	0		
1	09.52.18	26	25	-1		
1	09.52.24	26	27	1		
1	09.52.46	23	22	-1		





				the second is a second second second	
Date			10/12/2023		
Time			9:26 AM		
Site ID				KRKF	003
Location			K	irkland, Wa	ashington
Address			EB 80TH ST	T@ROSE	HILL ELEMENTARY
Posted Spee	ed Limit			20M	PH
Trigger Spe	ed Limit			26M	PH
Speed Type				Scho	ool
Lidar Techn	ician			Charles G	oodrich
AutoPatrol T	echnician		C	atherine T	hompson
Lidar Serial	Number		LP05509		
Radar Serial	Number		590-113/64095		
Detection Ty	/pe		Autopatrol-Radar Yes Yes Pass		
Measure Mo	de Captur	e			
Photo enfor	cement sig	ns present			
Pass/ Fail					
Ascending o	r Descend	ing	Descending		nding
City Lane	Times	Lidar Speeds	AP Speeds	Delta	Comments
1	09.26.21	18	17	-1	
1	09.30.26	18	17	-1	
1	09.30.56	19	18	-1	
1	09.31.30	15	15	0	
1	09.32.58	27	26	-1	





		and the second second second second			
Date			10/12/2023		
Time			9:34 AM		
Site ID				KRKF0	04
Location			Ki	rkland, Was	shington
Address			WB 80TH ST	T @ ROSE H	ILL ELEMENTARY
Posted Spee	ed Limit			20MP	н
Trigger Spe	A share and a share and a			26MP	н
Speed Type				Schoo	bl
Lidar Techni	the second s			Charles Go	odrich
AutoPatrol T	echnician		C	atherine Th	ompson
Lidar Serial	Number		LP05509		
Radar Serial	Number		590-113/66135 Autopatrol-Radar Yes		
Detection T	/pe				
Measure Mo	ode Captur	e			
Photo enfor	to enforcement signs present			Yes	
Pass/ Fail				Pass	
Ascending o	or Descend	ing		Descend	ding
City Lane	Times	Lidar Speeds	AP Speeds	Delta	Comments
1	09.34.33	24	25	1	
1	09.35.16	21	20	-1	
1	09.35.23	16	16	0	
1	09.36.09	27	26	-1	
1	09.36.44	22	22	0	





Date			10/12/2023		
Time			9:16 AM		
Site ID				KRKFO	05
Location			K	irkland, Wa	shington
Address			SB 724 STATE S	T @ LAKEVIEV	WELEMENTARY SCHOOL
Posted Spec	ed Limit			20MP	н
Trigger Spe	ed Limit			26MP	Н
Speed Type	and the second second second			Schoo	ol
Lidar Techn	ician			Charles Go	odrich
AutoPatrol T	echnician	Second and and	С	atherine Th	ompson
Lidar Serial	Number		LP05509		
Radar Serial	Number		590-113/68392 Autopatrol-Radar Yes Yes Pass		
Detection Ty	/pe				
Measure Mo	de Captur	e			
Photo enfor	cement sig	ns present			
Pass/ Fail					
Ascending o	r Descend	ing		Descent	ding
City Lane	Times	Lidar Speeds	AP Speeds	Deita	Comments
1	09.16.51	33	34	1	
1	09.16.58	21	20	-1	
1	09.17.11	18	18	0	
1	09.17.28	20	20	0	
1	09.17.41	20	19	-1	





Date			10/12/2023		
Time			9:14 AM		
Site ID	4. 5.2.2.	And States		KRKFO	06
Location			Ki	rkland, Was	hington
			WB 10600 NE	68TH ST @ LA	KEVIEW ELEMENTARY
Address				SCHOO	
Posted Spee	ed Limit			20MP	4
Trigger Spe	ed Limit	S. Masser		26MPI	H
Speed Type				Schoo	bl
Lidar Techni	ician			Charles Go	odrich
AutoPatrol T	echnician		Catherine Thompson		
Lidar Serial	Number		LP05509		
Radar Serial	Number		590-113/68391		
Detection T	/pe		Autopatrol-Radar		
Measure Mode Capture				Yes	
Photo enforcement signs present				Yes	
Pass/ Fail				Pass	
Ascending o	or Descend	ing		Descend	ling
City Lane	Times	Lidar Speeds	AP Speeds	Delta	Comments
1	09.14.08	21	22	1	
1	09.14.11	21	21	0	
1	09.14.21	17	17	0	
1	09.14.23	17	17	0	
1	09.14.26	16	15	-1	





Date			10/12/2023		
Time			10:17 AM		
Site ID				KRKFO	
Location			Ki	irkland, Was	
Location					
Address			NB 1203/ 841H A	THOREAU	DBURG ES / FINN HILL MS /
Posted Spee	d Limit			20MP	199
The second s	The second s			26MP	
Trigger Spec					
Speed Type	-1			School	Sector Se
Lidar Techni			Charles Goodrich		
AutoPatrol T			Catherine Thompson		
Lidar Serial		and the second	LP05509		
Radar Serial	Number		590-113/68421		
Detection Ty	pe		Autopatrol-Radar		
Measure Mo	de Captur	e	Yes		
Photo enfor	cement sig	ins present		Yes	
Pass/ Fail	Second Sec		Pass		
Ascending o	r Descend	ing		Descend	ding
City Lane	Times	Lidar Speeds	AP Speeds	Delta	Comments
1	10.17.19	17	16	-1	
1	10.17.48	23	24	1	
1	10.18.19	35	35	0	
1	10.21.35	17	16	-1	
1	10.22.58	30	30	0	





Date				10/12/20	023	
Time			10:25 AM			
Site ID			KRKF008			
Location	alway (		ĸ	irkland, Was	shington	
	F. Marsha		SB 14006 84TH A	VE NE @ SAND	DBURG ES / FINN HILL MS	
Address				THOREAU		
Posted Speed Limit				20MP	н	
Trigger Speed Limit				26MP	н	
Speed Type				Schoo	bl	
Lidar Technician			Charles Goodrich			
AutoPatrol Technician			Catherine Thompson			
Lidar Serial	Number		LP05509			
Radar Serial	Number		590-113/68429			
Detection Ty	/pe		Autopatrol-Radar			
Measure Mo	de Captur	e	Yes			
Photo enfor	cement sig	ns present	Yes			
Pass/ Fail			Pass			
Ascending o	or Descend	ing	Descending			
City Lane	Times	Lidar Speeds	AP Speeds	Delta	Comments	
1	10.25.12	31	31	0		
1	10.25.15	29	28	-1		
1	10.25.29	29	28	-1		
1	10.26.36	29	29	0		
1	10.27.47	29	29	0		



Report No.: 1910-071EA-174

Revision:

N/C

## Radar Sensor Calibration Verification Certificate of Calibration

FILED

Model: RRS24F-ST3

Part Number / Serial Number: 590-113/66806 Ex. 590-XXX / 6XXXX NOV 1 5 2023

KIRKLAND MUNICIPAL COURT

Description: Radar Characteristics Validation In compliance with: RRS24F-ST3 Radar Sensor Calibration Verification Procedure Documentation (5030-0150)

Date of Issue: January 11, 2023

Owner of EUT:

Verra Mobility 1150 N. Alma School Rd Mesa, AZ 85201

Attention of:

Engineering Department Phone: (480) 443-7000

Test Facility				
Test Laboratory	Keystone Compliance, LLC			
Address	131 North Columbus Innerbelt			
City, State, Zip Code	New Castle, PA 16101			
Phone	(724) 657-9940			
Email	emcteam@keystonecompliance.com			
Veb Site www.keystonecompliance.com				

	Test Personnel	
Name	Camren Morgan	
Title	EMC Test Engineer	
Signature	En my	

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Report No.: 1910-071EA-174

Revision:

N/C

### **Radar Sensor Calibration Verification Certificate of Calibration**

#### Model: RRS24F-ST3

### Part Number / Serial Number: 590-113/66806 Ex. 590-XXX / 6XXXX

Date of Issue: January 11, 2023

The frequency measurements performed and recorded within this report demonstrate that the JENOPTIK RR24F-ST3 radar has an accuracy of less than or equal to 0.62 mph in the range of 6.21 mph to 62.14 mph and an accuracy of 0.62 mph to 1.86 mph in the range of 62.14 mph to 186.41 mph. This is equal to or better than +/- 1 mph accuracy up to 100 mph, as specified by the manufacturer.

	FSK	<b>Frequency Set</b>	1		
Nominal Frequency (GHz)	Measured Frequency (GHz)	Amplitude (dBm)	Frequency Deviation (MHz)	Limit (MHz)	Results
f <sub>o</sub> = 24.08	24.078275	17.0778297	-1.72	+/- 48.2	PASS
f <sub>1</sub> = 24.08725	24.085424	17.3474424	-1.83	+/- 48.2	PASS
f <sub>2</sub> = 24.089	24.087376	18.3220724	-1.62	+/- 48.2	PASS
f <sub>3</sub> = 24.09	24.088351	18.547439	-1.65	+/- 48.2	PASS

	FSK	<b>Frequency Set</b>	2		10
Nominal Frequency (GHz)	Measured Frequency (GHz)	Amplitude (dBm)	Frequency Deviation (MHz)	Limit (MHz)	Results
f <sub>o</sub> = 24.12	24.118249	20.6862471	-1.75	+/- 48.2	PASS
f <sub>1</sub> = 24.12725	24.125725	21.0848535	-1.53	+/- 48.2	PASS
f <sub>2</sub> = 24.129	24.127351	21.7294888	-1.65	+/- 48.2	PASS
f <sub>3</sub> = 24.13	24.128326	22.4458445	-1.67	+/- 48.2	PASS

	FSK	<b>Frequency Set</b>	3		
Nominal Frequency (GHz)	Measured Frequency (GHz)	Amplitude (dBm)	Frequency Deviation (MHz)	Limit (MHz)	Results
f <sub>o</sub> = 24.16	24.157901	20.4036356	-2.10	+/- 48.2	PASS
f <sub>1</sub> = 24.16725	24.16505	21.0372457	-2.20	+/- 48.2	PASS
f <sub>2</sub> = 24.169	24.167	22.3278755	-2.00	+/- 48.2	PASS
f <sub>3</sub> = 24.17	24.167975	22.6032364	-2.03	+/- 48.2	PASS

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Report No.: 1910-071EA-220

Revision:

N/C

## **Radar Sensor Calibration Verification** Certificate of Calibration

Model: RRS24F-ST3

FILED

NOV 1 5 2023

Part Number / Serial Number: 590-113/61513 Ex. 590-XXX / 6XXXX

KIRKLAND MUNICIPAL COURT

Description: **Radar Characteristics Validation** In compliance with: RRS24F-ST3 Radar Sensor Calibration Verification Procedure Documentation (5030-0150)

> Date of Issue: June 19, 2023

Owner of EUT:

Verra Mobility 1150 N. Alma School Rd Mesa, AZ 85201

Attention of:

**Engineering Department** Phone: (480) 443-7000

Test Facility				
Test Laboratory	Keystone Compliance, LLC			
Address	131 North Columbus Innerbelt			
City, State, Zip Code	New Castle, PA 16101			
Phone	(724) 657-9940			
Email	emcteam@keystonecompliance.com			
Web Site				

	Test Personnel	
Name	Camren Morgan	
Title	EMC Test Engineer	
Signature	Erren drug	

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Report No.: 1910-071EA-220

Revision: N/C

### Radar Sensor Calibration Verification Certificate of Calibration

#### Model: RRS24F-ST3

Part Number / Serial Number: 590-113/61513 Ex. 590-XXX / 6XXXX

Date of Issue: June 19, 2023

The frequency measurements performed and recorded within this report demonstrate that the JENOPTIK RR24F-ST3 radar has an accuracy of less than or equal to 0.62 mph in the range of 6.21 mph to 62.14 mph and an accuracy of 0.62 mph to 1.86 mph in the range of 62.14 mph to 186.41 mph. This is equal to or better than +/- 1 mph accuracy up to 100 mph, as specified by the manufacturer.

	FSK	<b>Frequency Set</b>	1		
Nominal Frequency (GHz)	Measured Frequency (GHz)	Amplitude (dBm)	Frequency Deviation (MHz)	Limit (MHz)	Results
$f_0 = 24.08$	24.077951	1.07583065	-2.05	+/- 48.2	PASS
f <sub>1</sub> = 24.08725	24.085101	0.4834434	-2.15	+/- 48.2	PASS
f <sub>2</sub> = 24.089	24.08705	1.82907643	-1.95	+/- 48.2	PASS
$f_3 = 24.09$	24.088025	1.807434	-1.98	+/- 48.2	PASS

	FSK	Frequency Set	2		
Nominal Frequency (GHz)	Measured Frequency (GHz)	Amplitude (dBm)	Frequency Deviation (MHz)	Limit (MHz)	Results
$f_0 = 24.12$	24.118575	5.82124907	-1.43	+/- 48.2	PASS
f <sub>1</sub> = 24.12725	24.125725	5.14385949	-1.53	+/- 48.2	PASS
f <sub>2</sub> = 24.129	24.127676	5.90749047	-1.32	+/- 48.2	PASS
$f_3 = 24.13$	24.128651	5.66284744	-1.35	+/- 48.2	PASS

	FSK	Frequency Set	3		
Nominal Frequency (GHz)	Measured Frequency (GHz)	Amplitude (dBm)	Frequency Deviation (MHz)	Limit (MHz)	Results
$f_0 = 24.16$	24.158226	4.4716356	-1.77	+/- 48.2	PASS
f <sub>1</sub> = 24.16725	24.165376	5.84224569	-1.87	+/- 48.2	PASS
f <sub>2</sub> = 24.169	24.167326	6.93187163	-1.67	+/- 48.2	PASS
$f_3 = 24.17$	24.168301	7.18223101	-1.70	+/- 48.2	PASS

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27 <sup>4</sup>	REVENTIVE MAINTENANCE CHECKLIST ation: NB 132ND AVE NE @ MUIR ELEMENTARY/KAMIAKIN MIDDLE See Associated Ticket:	RT
Item	Status Note/Action (If Status N/A, please specify)	
1. Clean dirt, grime, and graffiti off enclosure and glass.		
1.1. Clean Graffiti.	Pass	
Check physical integrity. Check paint/housing for graffiti and (or) other vandalism.		
1.2. Clean Glass:	Pass	
Clean and inspect all glass and enclosures.		
1.3. Clean Enclosure (Interior):	Pass	
Clear vents/fans of obstruction. Remove dust and dirt by vacuum/wiping.		
1.4. Check Enclosure:	Pass	
If enclosure moved during cleaning, tighten base.		
2. Perform a general site inspection to include environmental and road conditions.		
2.1. PLP/Loop Loop:	N/A	
Check for exposed or cut loop wiring, and epoxy wear and tear.		
2.2. Power & Grounding:	Pass	
Inspect all power and grounding connections.		
2.3. Radar:	Pass	
Inspect radar and cables. Visually inspect antenna.		
2.4. WVDs:	N/A	
Check for popped out pucks, visible cracks, or other noticeable damage.		
3. Inspect poles, bases, and enclosures.		

3.1. Pole: Check sturdiness. Check hurricane collar and confirm screws are tight.	Pass
3.2. Base: Check for cracks. Ensure bolts (and latch bolt) are tight and secure inside base.	Pass
3.3. Enclosure: Confirm straps are tight and secure against pole. Tighten if loose.	Pass
4. Inspect cables and connections.	
4.1. Cables: Check all cables for visible wear or damage.	Pass
4.2. Connections: Check for exposed wires on pole connecting to radar, camera enclosure, and strobe.	Pass

5. Take (and attach) photo of enclosure, pole, and photo enforcement sign(s) for presence and damage.

5.1. Enclosure:



5.2. Pole:



5.3. Photo Enforcement Sign(s):



# FILED NOV 1 5 2023

VERRA MOBILITY PREVEN	KIRKLAND MUNICIPAL COURT PREVENTIVE MAINTENANCE CHECKLIST		
Date & Time: 10/12/2023 18:02:00 Site ID: KRKF002 Location: St	Location: SB 132ND AVE NE @ MUIR ELEMENTARY/KAMIAKIN MIDDLE		
Product: AutoPatrol Technician Name: Thomas Yuen		See Associated Ticket:	
ltem	Status	Note/Action (If Status N/A, please specify)	
1. Clean dirt, grime, and graffiti off enclosure and glass.			
1.1. Clean Graffiti.	Pass		
Check physical integrity. Check paint/housing for graffiti and (or) other vandalism.			
1.2. Clean Glass:	Pass		
Clean and inspect all glass and enclosures.			
1.3. Clean Enclosure (Interior):	Pass		
Clear vents/fans of obstruction. Remove dust and dirt by vacuum/wiping.			
1.4. Check Enclosure:	Pass		
If enclosure moved during cleaning, tighten base.	- 10 Maria		
2. Perform a general site inspection to include environmental and road conditions.			
2.1. PLP/Loop Loop:	N/A		
Check for exposed or cut loop wiring, and epoxy wear and tear.			
2.2. Power & Grounding:	Pass		
Inspect all power and grounding connections.			
2.3. Radar:	Pass		
Inspect radar and cables. Visually inspect antenna.			
2.4. WVDs:	N/A		
Check for popped out pucks, visible cracks, or other noticeable damage.			
3. Inspect poles, bases, and enclosures.			

3.1. Pole:	Pass
Check sturdiness. Check hurricane collar and confirm screws are tight.	
3.2. Base:	Pass
Check for cracks. Ensure bolts (and latch bolt) are tight and secure inside base.	
3.3. Enclosure:	Pass
Confirm straps are tight and secure against pole. Tighten if loose.	
4. Inspect cables and connections.	
4.1. Cables:	Pass
Check all cables for visible wear or damage.	
4.2. Connections:	Pass
Check for exposed wires on pole connecting to radar, camera enclosure, and strobe.	

5. Take (and attach) photo of enclosure, pole, and photo enforcement sign(s) for presence and damage.



5.2. Pole:



5.1. Enclosure:



