

# CERTIFICATE CONCERNING DESIGN AND CONSTRUCTION OF ELECTRONIC UNICIPAL COURT SPEED MEASURING DEVICES

I, Lesieli Casale, do certify under penalty of the laws of the State of Washington that the following is true and correct:

I have been employed as a technician by American Traffic Solutions for 2 years. I became a speed validation technician on January 12, 2023 and have over 100 hours performing speed validation tests. I am nationally certified as a RADAR and LIDAR operator. The City of Kirkland currently uses the AutoPatrol<sup>TM</sup> 3D radar fixed speed safety camera system, an electronic speed measuring device provided through a contract with American Traffic Solutions, Inc. ("ATS"). Part of my duties include monitoring regular testing of the AutoPatrol 3D radar fixed speed safety camera systems used by the City of Kirkland.

ATS contracted with the City of Kirkland to provide an Automated Speed Enforcement ("ASE") system designed to record the speed of a vehicle and obtain photographs or other recorded images of the vehicle and the vehicle's registration plate while the vehicle is traveling in excess of speed limits in certain safety zones within posted limits.

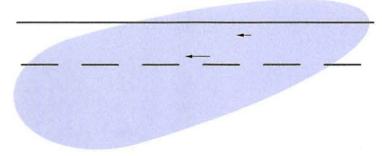
The ASE program includes the use of the AutoPatrol 3D radar fixed speed safety camera systems at the following locations within the City of Kirkland:

Location Code	Location Description	Lanes Monitored
KRKF001	NB 132ND AVE NE @ MUIR ELEMENTARY/KAMIAKIN MIDDLE	1
KRKF002	SB 132ND AVE NE @ MUIR ELEMENTARY/KAMIAKIN MIDDLE	1
KRKF003	EB 80TH ST @ ROSE HILL ELEMENTARY	1
KRKF004	WB 80TH ST @ ROSE HILL ELEMENTARY	1
KRKF005	SB 724 STATE ST @ LAKEVIEW ELEMENTARY SCHOOL	1
KRKF006	WB 10600 NE 68TH ST @ LAKEVIEW ELEMENTARY SCHOOL	1
KRKF007	NB 12637 84TH AVE NE @ SANDBURG ES / FINN HILL MS / THOREAU ES	1
KRKF008	SB 14006 84TH AVE NE @ SANDBURG ES / FINN HILL MS / THOREAU ES	1

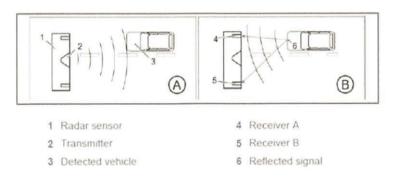
The AutoPatrol 3D radar fixed speed safety camera system operates by measuring vehicle speed, as well as position relative to the radar to calculate and differentiate multiple vehicles in the radar beam. The speed of a moving vehicle is measured by Doppler radar. Doppler radar is a generally accepted technology used for measuring speed. The AutoPatrol 3D radar technology is used throughout the US and Europe as well as other countries and is approved by the Swiss national metrology institute- METAS.

The AutoPatrol 3D radar fixed speed safety camera system uses a tracking radar sensor for measuring vehicle speeds and detecting speed violations. The AutoPatrol 3D radar is aligned at a fixed angle across the road. The AutoPatrol 3D radar emits a horizontal beam over the road surface as represented by the illustration below. The tracking radar can simultaneously detect multiple vehicles and measure their speed, distance, angle and movement within the radar beam. The radar tracks multiple vehicles by reconstructing vehicle movement from the measured object speed, angle and distance values. If a vehicle passes a defined trigger line, the radar

outputs the vehicle's speed and lane information. The camera connected to the tracking radar uses this information to determine if there is a speed violation and to capture photographs showing the measured speed and lane on the databar of the captured images.



The tracking radar utilizes the Doppler Effect for speed determination. If an electromagnetic wave is emitted at a moving object, then the wave is reflected back from the moving object. The frequency of the wave received back by the radar shifts based on the speed of the moving object and its direction of travel. The tracking radar continuously determines this frequency shift of each object to calculate the object's speed. The tracking radar consists of two receiving antennas integrated into a single radar sensor. This configuration allows the radar to measure the distance and angle of the vehicle relative to the position of the radar sensor. Illustration A and B show the measurement principle in simplified form. The radar sensor emits a radar beam (illustration A). The radar beam is reflected by the vehicle (illustration B). The two receivers receive the reflected radar beam. The radar sensor evaluates the return frequency, as well as the phase difference of the reflected radar beam from both of the receivers. With the aid of these values the radar sensor calculates the vehicle position.



Prior to operation each day, the system performs a system self-test. This self-test performs an electronic tuning fork test to produce a specific frequency and returns an associated speed value. Only if the return value meets the acceptance criteria to show that the system is operating correctly will the system enter measure mode. Unless a self-test is successful, the system will not enter measure mode and no violations will be captured. Additional information stored as metadata within each image includes coordinates of the vehicle position at the time of capture. This information is extracted and utilized through a secondary speed verification process to provide yet another means to validate offender speed and position based on the two images obtained and image analytics. In addition to the internal system checks and the manufacturer calibration certification, the 3D radar system is subject to routine and independent calibration check of the speeds produced by the system at least annually by a qualified technician.

Each day the computer which controls the fixed speed safety camera system is rebooted. The reboot is initiated each day and each time the computer is rebooted an internal check is performed on all operations of

each fixed speed safety camera system, including the clocks, sensors, camera and speed calculating hardware and software, in order to verify that all operations are functioning correctly. When the internal check detects a problem with one of the operations on a given fixed speed safety camera system, then that particular fixed speed safety camera system is inactivated and a request for service is relayed to ATS support personnel. This means that violations cannot be issued until any internal problem is fixed.

Speed validation tests are regularly performed on each installed and operable AutoPatrol 3D radar fixed speed safety camera system. The test is conducted by having a LIDAR Operator obtain true measurements of up to five vehicles per lane in the ascending and/or descending direction. The speed of the vehicle is captured by the LIDAR Operator and then relayed via cellular to an ATS Technician. The ATS Technician then compares the vehicle speed measured by the AutoPatrol 3D radar fixed speed safety camera system to the speed measured by the LIDAR Operator to ensure the accuracy of the AutoPatrol 3D radar fixed speed safety camera system. ATS maintains the results of each test in a Validation Report. The speed validation for each system was performed on the following date and the systems at each location were found to be in proper working order:

Location Code	Location Description	Date of Test
KRKF001	NB 132ND AVE NE @ MUIR ELEMENTARY/KAMIAKIN MIDDLE	10/12/2023
KRKF002	SB 132ND AVE NE @ MUIR ELEMENTARY/KAMIAKIN MIDDLE	10/12/2023
KRKF003	EB 80TH ST @ ROSE HILL ELEMENTARY	10/12/2023
KRKF004	WB 80TH ST @ ROSE HILL ELEMENTARY	10/12/2023
KRKF005	SB 724 STATE ST @ LAKEVIEW ELEMENTARY SCHOOL	10/12/2023
KRKF006	WB 10600 NE 68TH ST @ LAKEVIEW ELEMENTARY SCHOOL	10/12/2023
KRKF007	NB 12637 84TH AVE NE @ SANDBURG ES / FINN HILL MS / THOREAU ES	10/12/2023
KRKF008	SB 14006 84TH AVE NE @ SANDBURG ES / FINN HILL MS / THOREAU ES	10/12/2023

Preventative maintenance, including visual inspections, is regularly performed on the AutoPatrol 3D radar fixed speed safety camera systems. Preventative maintenance activities include: cleaning of the cameras and housing, general site inspection of environment and road conditions, inspection of poles, bases and enclosures, and inspection of system cables and connections. The location and date that preventative maintenance is performed is recorded in the Preventative Maintenance Log, which along with the Validation Report(s) referenced above, is attached hereto.

I am a custodian, or otherwise qualified witness, as to the attached records. I make this declaration based on personal knowledge, and if called and sworn as a witness, I could and would testify as set forth in the following paragraph.

Attached as Exhibits are: Exhibit A - Speed Validation Reports, Exhibit B - Preventative Maintenance Logs, and Exhibit C - Annual System Verification Certificate for all AutoPatrol 3D radar fixed speed safety camera systems installed and used by the City of Kirkland. All documents and materials included as Exhibit A, Exhibit B and Exhibit C are authentic and are what they purport to be, and accurately describe the matters set forth therein. All such records are business records in that they are: (1) records kept in the ordinary course of business; (2) created at or near the time of the transactions or events reflected therein by, or based on

information from, a person with knowledge of the transaction or events; and (3) kept as part of a regular business activity.

Based upon my education, training, experience, and knowledge of the AutoPatrol 3D radar fixed speed safety camera system, it is my opinion that the system is so designed and constructed as to accurately employ measurement techniques based on a division of distance over time in such a manner that it will give accurate measurements of the speed of motor vehicles.

I, Lesieli Casale, certify (or declare) under penalty of perjury under the laws of the State of Washington that the foregoing is true and correct.

Dated this 9th day of November 2023 in Mesa, Arizona

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Lesieli Casale

Lesieli Casale, Speed Validation Technician



#### Speed Validation Report Client: Kirkland, WA

FILED

NOV 1 5 2023

Validation Date: October 12, 2023

KRKF001 - NB 132ND AVE NE @ MUIR ELEMENTARY/KAMIAKIN MIDDLE

o Radar Serial Number: 590-113/66806

KRKF002 – SB 132ND AVE NE @ MUIR ELEMENTARY/KAMIAKIN MIDDLE

o Radar Serial Number: 590-113/61513

KRKF003 – EB 80TH ST @ ROSE HILL ELEMENTARY

o Radar Serial Number: 590-113/64095

KRKF004 – WB 80TH ST @ ROSE HILL ELEMENTARY

o Radar Serial Number: 590-113/66135

KRKF005 – SB 724 STATE ST @ LAKEVIEW ELEMENTARY SCHOOL

Radar Serial Number: 590-113/68392

KRKF006 – WB 10600 NE 68TH ST @ LAKEVIEW ELEMENTARY SCHOOL

o Radar Serial Number: 590-113/68391

KRKF007 – NB 12637 84TH AVE NE @ SANDBURG ES / FINN HILL MS / THOREAU ES

o Radar Serial Number: 590-113/68421

KRKF008 – SB 14006 84TH AVE NE @ SANDBURG ES / FINN HILL MS / THOREAU ES

o Radar Serial Number: 590-113/68429

#### Equipment:

Pro-Lite Plus Hand held Lidar Serial Number: LP05509

Certification Date: October 27, 2022 Lidar Operator: Charles Goodrich

RLC Operator: Catherine Koselka-Thompson



A speed validation test was conducted for the sites listed above. The Lidar Operator, obtained true measurements of five vehicles per lane in the ascending and/or descending direction. Those speeds were obtained using a Kustom Signals Pro-Lite+ hand held Lidar instrument. The speed of the vehicle is captured by the Lidar Operator and then relayed via cellular to the RLC Technician. The RLC Technician is monitoring the vehicle speed at the Fixed Speed Camera system simultaneously to ensure the accuracy of the system. The speed validation tests performed on the above-listed dates confirmed the accuracy of the Fixed Speed Camera systems at each location.

I, Lesieli Casale, certify that the information contained in this report is true and accurate.

Signed:

Date: November 9, 2023

Lesieli Casale

Mesa, Arizona

American Traffic Solutions Speed Integrity Team



# Certificate of Achievement

# Speed Integrity Technician Has successfully completed the 16 hour course for

Speed Integrity Technician

This course encompasses all the necessary tasks required to perform the duties as a Speed Integrity Technician. Through this course each participant is required to display the proper competency through written and practical examinations. In addition, this course certifies each participants as a Lidar operator.

Charles Goodrich

March 29, 2016 This Day:

American Traffic Solutions

Police Traffic Laser/Radar Instructor

n Traffic Solutions, Inc., 7681 East Gray Road, Scottsdate, AZ 85260

# Certificate of Achievement

Speed Integrity Technician

Has successfully completed the course for Speed Inegrity Technician

This course encompasses all the necessary tasks required to perform the duties as a Speed Integrity Technician. Through this course each participant is required to display the proper competencies in Radar and Laser Technology. In addition, this course certifies each participants as a Radar and Lidar operator.

Catherine Koselka Presented to:

August 21st, 2019 This Day:

American Traffic Solutions

Tylor Yochim

Tyle Vol

RDLD Certificate of Achievement, V1.0

American Traffic Solutions, Inc., 7681 East Gray Road, Scottsdale, AZ 85260

Certificate # VCC-0821-AZ-02



#### PB Electronics Inc.

248 W Peaceful Ct., Shepherdsville, KY 40165
502 543-7032 www.pbelectronics.com
Factory Authorized Calibration Center for Stalker, MPH, Kustom, and LTI

### Certificate of Calibration

Manufacturer: Kustom

Model: ProLite

Serial Number: LP05509

I hereby certify that this Speed Measuring Device has been checked for accuracy and correctness of operation under my supervision. This Speed Measuring Device is certified accurately within +/- 0.5 mph in stationary mode using equipment traceable to National Institute of Standards and technology.

The laser transmitter of this device has been tested and found to be within specified range for Laser Devices as established by the Federal Communications Commission and IACP.

FCC License number PG-18-12552

Technician Signature



Date: October 27, 2022





# SELF-ACCURACY TEST Kustom Signals Pro-Lite+ Lidar Speed Measurement Tool

DATE: October 12, 2023
Start of shift "Self-Diagnostic test" time:9:09 AM
Start of shift Distance check:100'lidar
End of shift "Self-Diagnostic test" time:10:32 AM
End of shift Distance check:100'
City and State:Kirkland, WA
Lidar Serial Number:LP05509
Certification Date:October 27th, 2022
OPERATOR:Charles Goodrich
I, Charles Goodrich, certify that the Kustom Signals Pro-Lite+ Lidar speed measurement device was setup, tested, and operated in accordance with the manufactures specifications to include its self-diagnostic check.
Further, I certified that the self-check distance was completed and accurate.
Signature: October 12, 2023





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Date				10/12/2	023
Time			9:48 AM		
Site ID				KRKF0	01
Location			Ki	rkland, Wa	shington
			NB 132ND AVE	NE @ MUIR E	LEMENTARY/KAMIAKIN
Address				MIDDL	E
Posted Spee	ed Limit			20MP	Н
Trigger Spe	ed Limit			26MP	Н
Speed Type				Schoo	ol
Lidar Techni			Charles Goodrich		
AutoPatrol T	echnician		Catherine Thompson		
Lidar Serial Number			LP05509		
Radar Serial	A TARREST CONTRACTOR		590-113/66806		
Detection T			Autopatrol-Radar		
Measure Mode Capture				Yes	
Photo enforcement signs present				Yes	
Pass/ Fail				Pass	i
Ascending or Descending				Descen	ding
City Lane	Times	Lidar Speeds	AP Speeds	Delta	Comments
1	09.48.04	17	18	1	
1	09.48.10	22	21	-1	
1	09.48.20	20	20	0	
1	09.49.57	41	41	0	
1	09.50.12	24	24	0	





Date				10/12/20	)23
Time			9:51 AM		
Site ID				KRKF0	02
Location				Kirkland,	WA
			SB 132ND AVE	NE @ MUIR EI	LEMENTARY/KAMIAKIN
Address				MIDDLE	E
Posted Spec	ed Limit			20MPI	Н
Trigger Spe	ed Limit			26MPI	Н
Speed Type				Schoo	ol
Lidar Techn	ician		19	Charles Go	odrich
AutoPatrol Technician			Catherine Thompson		
Lidar Serial Number			LP05509		
Radar Serial Number			590-113/61513		
Detection Type				Autopatrol-	Radar
Measure Mode Capture				Yes	
Photo enforcement signs present				Yes	
Pass/ Fail				Pass	
Ascending of	r Descend	ing		Descend	ling
City Lane	Times	Lidar Speeds			
1	09.51.33	29	29	0	
1	09.52.09	28	28	0	
1	09.52.18	26	25	-1	
1	09.52.24	26	27	1	
1	09.52.46	23	22	-1	





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Date				10/12/20	)23	
Time			9:26 AM			
Site ID				KRKF0	03	
Location			Ki	rkland, Was	hington	
Address			EB 80TH ST	(@ ROSE H	ILL ELEMENTARY	
Posted Spe	ed Limit			20MP	H'	
Trigger Spe	ed Limit			26MP	Н	
Speed Type				Schoo	) I	
Lidar Techn	ician			Charles Go	odrich	
AutoPatrol 1	echnician		Catherine Thompson			
Lidar Serial	idar Serial Number			LP05509		
Radar Seria	Radar Serial Number			590-113/64095		
Detection Ty	/pe		Autopatrol-Radar			
Measure Mo	easure Mode Capture			Yes		
Photo enforcement signs present				Yes		
Pass/ Fail				Pass		
Ascending of	r Descend	ing		Descend	ling	
City Lane	Times	Lidar Speeds	AP Speeds Delta Comments			
1	09.26.21	18	17	-1		
1	09.30.26	18	17	-1		
1	09.30.56	19	18	-1		
1	09.31.30	15	15	0		
1	09.32.58	27	26	-1		





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Date				10/12/20	023	
Time			9:34 AM			
Site ID				KRKF0	04	
Location			Ki	rkland, Was	shington	
Address			WB 80TH S	T@ ROSE H	HILL ELEMENTARY	
Posted Spee	ed Limit			20MP	Н	
Trigger Spe				26MP	H	
Speed Type	THE REAL PROPERTY OF THE PARTY			Schoo	ol	
Lidar Techni			LÃ	Charles Go	odrich	
AutoPatrol T	echnician		C	atherine Th	ompson	
Lidar Serial	Lidar Serial Number			LP05509		
Radar Serial	Radar Serial Number			590-113/66135		
Detection Ty	/pe		Autopatrol-Radar			
Measure Mo	ode Capture Yes					
Photo enforcement signs present				Yes		
Pass/ Fail				Pass		
Ascending or Descending				Descend	ding	
City Lane	Times	Lidar Speeds	AP Speeds	Delta	Comments	
1	09.34.33	24	25	1		
1	09.35.16	21	20	-1		
1	09.35.23	16	16	0		
1	09.36.09	27	26	-1		
1	09.36.44	22	22	0		





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Date				10/12/20	023	
Time			9:16 AM			
Site ID				KRKF0	05	
Location			Ki	rkland, Was	shington	
Address			SB 724 STATE S	T@LAKEVIEV	W ELEMENTARY SCHOOL	
Posted Spe	ed Limit			20MP	H	
Trigger Spe	ed Limit			26MP	Н	
Speed Type				Schoo	ol	
Lidar Techn	ician			Charles Go	odrich	
AutoPatrol 1	AutoPatrol Technician			Catherine Thompson		
Lidar Serial	Lidar Serial Number			LP05509		
Radar Serial	Radar Serial Number			590-113/68392		
Detection T	Detection Type			Autopatrol-Radar		
Measure Mo	ode Captur	e		Yes		
Photo enforcement signs present  Pass/ Fail				Yes		
				Pass		
Ascending of	r Descend	ing		Descend	ding	
City Lane	Times	Lidar Speeds	AP Speeds Delta Comments			
1	09.16.51	33	34	1		
1	09.16.58	21	20	-1		
1	09.17.11	18	18	0		
1	09.17.28	20	20	0		
1	09.17.41	20	19	-1		





		Speed vall	uation work	SHEEL	
Date			10/12/2023		
Time			9:14 AM		
Site ID				KRKFO	006
Location			Ki	rkland, Wa	shington
Address			WB 10600 NE	68TH ST @ L/ SCHOO	AKEVIEW ELEMENTARY DL
Posted Spee	ed Limit			20MP	H
Trigger Spe	ed Limit			26MP	H
Speed Type				Scho	ol
Lidar Techni	ician		Charles Goodrich		
AutoPatrol Technician			Catherine Thompson		
Lidar Serial	Number		LP05509		
Radar Serial	Number			590-113/6	8391
Detection Type				Autopatrol	-Radar
Measure Mode Capture				Yes	
Photo enforcement signs present				Yes	i
Pass/ Fail				Pass	5
Ascending of	r Descend	ing		Descen	ding
City Lane	Times	Lidar Speeds	AP Speeds Delta Comments		
1	09.14.08	21	22	1	
1	09.14.11	21	21	0	
1	09.14.21	17	17	0	
1	09.14.23	17	17	0	
1	09.14.26	16	15	-1	





		epoca van	dation Work	tonicot		
Date			10/12/2023			
Time			10:17 AM			
Site ID				KRKF0	07	
Location			K	irkland, Was	shington	
			NB 12637 84TH A	VE NE @ SAND	DBURG ES / FINN HILL MS /	
Address				THOREAU		
Posted Spee	ed Limit			20MPI	Н	
Trigger Spe	ed Limit			26MPI	Н	
Speed Type				Schoo	ol	
Lidar Techni	Lidar Technician			Charles Goodrich		
AutoPatrol Technician			Catherine Thompson			
Lidar Serial Number			LP05509			
Radar Serial	Radar Serial Number			590-113/68421		
Detection Ty	/pe		Autopatrol-Radar			
Measure Mode Capture				Yes		
Photo enforcement signs present				Yes		
Pass/ Fail				Pass		
Ascending or Descending				Descend	ding	
City Lane	Times	Lidar Speeds	AP Speeds	Delta	Comments	
1	10.17.19	17	16	-1		
1	10.17.48	23	24	1		
1	10.18.19	35	35	0		
1	10.21.35	17	16	-1		
1	10.22.58	30	30	0		





		Speed Vall	dation work	sneet	
Date				10/12/	2023
Time			10:25 AM		
Site ID				KRKF	008
Location			Ki	rkland, W	ashington
Address			SB 14006 84TH A	VE NE @ SAI	NDBURG ES / FINN HILL MS / Au es
Posted Spee	ed Limit			20M	PH
Trigger Spe	ed Limit			26M	PH
Speed Type				Scho	ool
Lidar Techni	ician		Charles Goodrich		
AutoPatrol T	echnician		Catherine Thompson		
Lidar Serial	Number		LP05509		
Radar Serial	Number		590-113/68429		
Detection Ty	ре		Autopatrol-Radar		
Measure Mo	de Captur	е	Yes		
Photo enfor	cement sig	ns present		Ye	s
Pass/ Fail				Pas	S
Ascending o	r Descend	ing		Descei	nding
City Lane	Times	Lidar Speeds	AP Speeds Delta Comments		
1	10.25.12	31	31	0	
1	10.25.15	29	28	-1	
1	10.25.29	29	28	-1	
1	10.26.36	29	29	0	
1	10.27.47	29	29	0	



1910-071EA-223

Revision:

N/C

# Radar Sensor Calibration Verification Certificate of Calibration

Model: RRS24F-ST3

Part Number / Serial Number: 590-113/68392 Ex. 590-XXX / 6XXXX FILED NOV 1 5 2023

MUNICIPAL COURT

Description:

Radar Characteristics Validation In compliance with:

RRS24F-ST3 Radar Sensor Calibration Verification Procedure Documentation (5030-0150)

Date of Issue:

July 11, 2023

Owner of EUT:

Verra Mobility

1150 N. Alma School Rd

Mesa, AZ 85201

Attention of:

**Engineering Department** 

Phone: (480) 443-7000

Test Facility				
Test Laboratory	Keystone Compliance, LLC			
Address	131 North Columbus Innerbelt			
City, State, Zip Code	New Castle, PA 16101			
Phone	(724) 657-9940			
Email	emcteam@keystonecompliance.com			
Web Site	www.keystonecompliance.com	***		

	Test Personnel
Name	Camren Morgan
Title	EMC Test Engineer
Signature	Erun my

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Revision:

N/C

# Radar Sensor Calibration Verification Certificate of Calibration

Model: RRS24F-ST3

Part Number / Serial Number: 590-113/68392 Ex. 590-XXX / 6XXXX

Date of Issue:

July 11, 2023

The frequency measurements performed and recorded within this report demonstrate that the JENOPTIK RR24F-ST3 radar has an accuracy of less than or equal to 0.62 mph in the range of 6.21 mph to 62.14 mph and an accuracy of 0.62 mph to 1.86 mph in the range of 62.14 mph to 186.41 mph. This is equal to or better than +/- 1 mph accuracy up to 100 mph, as specified by the manufacturer.

FSK Frequency Set 1						
Nominal Frequency (GHz)	Measured Frequency (GHz)	Amplitude (dBm)	Frequency Deviation (MHz)	Limit (MHz)	Results	
$f_0 = 24.08$	24.078275	2.66783365	-1.72	+/- 48.2	PASS	
f <sub>1</sub> = 24.08725	24.085424	2.4324414	-1.83	+/- 48.2	PASS	
f <sub>2</sub> = 24.089	24.087376	3.96707643	-1.62	+/- 48.2	PASS	
f <sub>3</sub> = 24.09	24.088351	4.290435	-1.65	+/- 48.2	PASS	

FSK Frequency Set 2						
Nominal Frequency (GHz)	Measured Frequency (GHz)	Amplitude (dBm)	Frequency Deviation (MHz)	Limit (MHz)	Results	
f <sub>o</sub> = 24.12	24.118901	6.15425007	-1.10	+/- 48.2	PASS	
f <sub>1</sub> = 24.12725	24.12605	5.20085849	-1.20	+/- 48.2	PASS	
f <sub>2</sub> = 24.129	24.128	5.95248847	-1.00	+/- 48.2	PASS	
$f_3 = 24.13$	24.128975	6.01584444	-1.02	+/- 48.2	PASS	

FSK Frequency Set 3						
Nominal Frequency (GHz)	Measured Frequency (GHz)	Amplitude (dBm)	Frequency Deviation (MHz)	Limit (MHz)	Results	
f <sub>o</sub> = 24.16	24.158876	4.6666356	-1.12	+/- 48.2	PASS	
f <sub>1</sub> = 24.16725	24.166025	5.54624869	-1.22	+/- 48.2	PASS	
f <sub>2</sub> = 24.169	24.167975	6.85487563	-1.03	+/- 48.2	PASS	
$f_3 = 24.17$	24.16895	7.18723601	-1.05	+/- 48.2	PASS	



1910-071EA-223

Revision:

N/C

# Radar Sensor Calibration Verification Certificate of Calibration

FILED
NOV 1 5 2023

Model: RRS24F-ST3

KIRKLAND MUNICIPAL COURT

Part Number / Serial Number: 590-113/68391 Ex. 590-XXX / 6XXXX

Description:

Radar Characteristics Validation

In compliance with:

RRS24F-ST3 Radar Sensor Calibration Verification Procedure Documentation (5030-0150)

Date of Issue:

July 11, 2023

Owner of EUT:

Verra Mobility

1150 N. Alma School Rd

Mesa, AZ 85201

Attention of:

**Engineering Department** 

Phone: (480) 443-7000

Test Facility				
Test Laboratory	Keystone Compliance, LLC			
Address	131 North Columbus Innerbelt			
City, State, Zip Code	New Castle, PA 16101			
Phone	(724) 657-9940			
Email	emcteam@keystonecompliance.com			
Web Site	www.keystonecompliance.com			

Test Personnel				
Name	Camren Morgan			
Title	EMC Test Engineer			
Signature	Erun dry			

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1910-071EA-223

Revision:

N/C

# Radar Sensor Calibration Verification Certificate of Calibration

Model: RRS24F-ST3

Part Number / Serial Number: 590-113/68391 Ex. 590-XXX / 6XXXX

Date of Issue:

July 11, 2023

The frequency measurements performed and recorded within this report demonstrate that the JENOPTIK RR24F-ST3 radar has an accuracy of less than or equal to 0.62 mph in the range of 6.21 mph to 62.14 mph and an accuracy of 0.62 mph to 1.86 mph in the range of 62.14 mph to 186.41 mph. This is equal to or better than +/- 1 mph accuracy up to 100 mph, as specified by the manufacturer.

FSK Frequency Set 1						
Nominal Frequency (GHz)	Measured Frequency (GHz)	Amplitude (dBm)	Frequency Deviation (MHz)	Limit (MHz)	Results	
f <sub>o</sub> = 24.08	24.078275	15.0058307	-1.72	+/- 48.2	PASS	
f <sub>1</sub> = 24.08725	24.08575	15.8904414	-1.50	+/- 48.2	PASS	
f <sub>2</sub> = 24.089	24.087376	17.3990754	-1.62	+/- 48.2	PASS	
f <sub>3</sub> = 24.09	24.088351	17.750434	-1.65	+/- 48.2	PASS	

FSK Frequency Set 2						
Nominal Frequency (GHz)	Measured Frequency (GHz)	Amplitude (dBm)	Frequency Deviation (MHz)	Limit (MHz)	Results	
f <sub>0</sub> = 24.12	24.118249	16.5232451	-1.75	+/- 48.2	PASS	
f <sub>1</sub> = 24.12725	24.125401	16.2448575	-1.85	+/- 48.2	PASS	
f <sub>2</sub> = 24.129	24.127025	17.4124875	-1.98	+/- 48.2	PASS	
$f_3 = 24.13$	24.128326	17.7438484	-1.67	+/- 48.2	PASS	

FSK Frequency Set 3					
Nominal Frequency (GHz)	Measured Frequency (GHz)	Amplitude (dBm)	Frequency Deviation (MHz)	Limit (MHz)	Results
f <sub>o</sub> = 24.16	24.158226	16.7786356	-1.77	+/- 48.2	PASS
f <sub>1</sub> = 24.16725	24.165376	17.2772437	-1.87	+/- 48.2	PASS
f <sub>2</sub> = 24.169	24.167	18.6498746	-2.00	+/- 48.2	PASS
$f_3 = 24.17$	24.168301	18.891231	-1.70	+/- 48.2	PASS





#### KIRKLAND MUNICIPAL COURT

#### PREVENTIVE MAINTENANCE CHECKLIST

Date & Time: 10/22/2023 14:56:00	Site ID: KRKF005	F005 Location: SB 724 STATE ST @ LAKEVIEW ELEMENTARY SCHOOL		
Product: AutoPatrol	Technicia	n Name: Thomas Yuen See Associated Ti	cket:	

ltem:	Status	Note/Action (If Status N/A, please specify)
Clean dirt, grime, and graffiti off enclosure and glass.		
1.1. Clean Graffiti.	Pass	
Check physical integrity. Check paint/housing for graffiti and (or) other vandalism.		
1.2. Clean Glass:	Pass	
Clean and inspect all glass and enclosures.		
1.3. Clean Enclosure (Interior):	Pass	
Clear vents/fans of obstruction. Remove dust and dirt by vacuum/wiping.		
1.4. Check Enclosure:	Pass	
If enclosure moved during cleaning, tighten base.		
Perform a general site inspection to include environmental and road conditions.		
2.1. PLP/Loop Loop:	N/A	
Check for exposed or cut loop wiring, and epoxy wear and tear.		
2.2. Power & Grounding:	Pass	
Inspect all power and grounding connections.		
2.3. Radar:	Pass	
Inspect radar and cables. Visually inspect antenna.		
2.4. WVDs:	N/A	
Check for popped out pucks, visible cracks, or other noticeable damage.		
3. Inspect poles, bases, and enclosures.		

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3.1. Pole: Check sturdiness. Check hurricane collar and confirm screws are tight.	Pass
3.2. Base: Check for cracks. Ensure bolts (and latch bolt) are tight and secure inside base.	Pass
3.3. Enclosure:  Confirm straps are tight and secure against pole. Tighten if loose.	Pass
Inspect cables and connections.	
4.1. Cables: Check all cables for visible wear or damage.	Pass
4.2. Connections:  Check for exposed wires on pole connecting to radar, camera enclosure, and strobe.	Pass

5. Take (and attach) photo of enclosure, pole, and photo enforcement sign(s) for presence and damage.





5.2. Pole:





5.3. Photo Enforcement Sign(s):





KIRKLAND MUNICIPAL COURT

#### PREVENTIVE MAINTENANCE CHECKLIST

Date & Time: 10/22/2023 14:43:00 Site ID: KRKF006 Location: WB 10600 NE 68TH ST @ LAKEVIEW ELEMENTARY SCHOOL

Product: AutoPatrol Technician Name: Thomas Yuen See Associated Ticket:

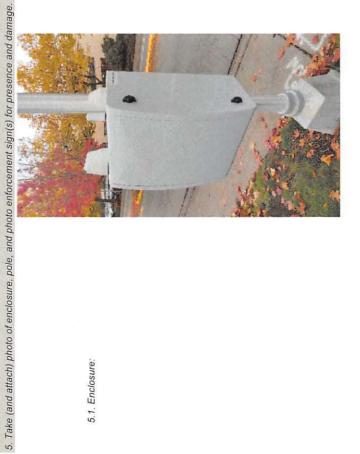
ltem	Status	Note/Action (If Status N/A, please specify)
Clean dirt, grime, and graffiti off enclosure and glass.		
1.1. Clean Graffiti.	N/A	
Check physical integrity. Check paint/housing for graffiti and (or) other vandalism.		
1.2. Clean Glass:	Pass	
Clean and inspect all glass and enclosures.		
1.3. Clean Enclosure (Interior):	N/A	
Clear vents/fans of obstruction. Remove dust and dirt by vacuum/wiping.		
1.4. Check Enclosure:	N/A	
If enclosure moved during cleaning, tighten base.		
Perform a general site inspection to include environmental and road conditions.		
2.1. PLP/Loop Loop:		
Check for exposed or cut loop wiring, and epoxy wear and tear.		
2.2. Power & Grounding:	N/A	
Inspect all power and grounding connections.		
2.3. Radar:	N/A	
Inspect radar and cables. Visually inspect antenna.		
2.4. WVDs:		
Check for popped out pucks, visible cracks, or other noticeable damage.		
3. Inspect poles, bases, and enclosures.		

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3.1. Pole:  Check sturdiness. Check hurricane collar and confirm screws are tight.	N/A
3.2. Base:	N/A
Check for cracks. Ensure bolts (and latch bolt) are tight and secure inside base.	
3.3. Enclosure:	N/A.
Confirm straps are tight and secure against pole. Tighten if loose.	
4. Inspect cables and connections.	
4.1. Cables:	N/A
Check all cables for visible wear or damage.	
4.2. Connections:	N/A
Check for exposed wires on pole connecting to radar, camera enclosure, and strobe.	



5.2. Pole:



5.1. Enclosure:

5.3. Photo Enforcement Sign(s):

