

CERTIFICATE CONCERNING DESIGN AND CONSTRUCTION OF ELECTRONIC SPEED MEASURING DEVICES

I, Lesieli Casale, do certify under penalty of the laws of the State of Washington that the following is true and correct:

I have been employed as a technician by American Traffic Solutions for 2 years. I became a speed validation technician on January 12, 2023 and have over 100 hours performing speed validation tests. I am nationally certified as a RADAR and LIDAR operator. The City of Kirkland currently uses the AutoPatrolTM 3D radar fixed speed safety camera system, an electronic speed measuring device provided through a contract with American Traffic Solutions, Inc. ("ATS"). Part of my duties include monitoring regular testing of the AutoPatrol 3D radar fixed speed safety camera systems used by the City of Kirkland.

ATS contracted with the City of Kirkland to provide an Automated Speed Enforcement ("ASE") system designed to record the speed of a vehicle and obtain photographs or other recorded images of the vehicle and the vehicle's registration plate while the vehicle is traveling in excess of speed limits in certain safety zones within posted limits.

The ASE program includes the use of the AutoPatrol 3D radar fixed speed safety camera systems at the following locations within the City of Kirkland:

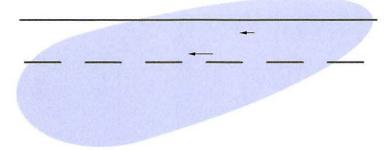
Location Code	Location Description	Lanes Monitored
KRKF001	NB 132ND AVE NE @ MUIR ELEMENTARY/KAMIAKIN MIDDLE	1
KRKF002	SB 132ND AVE NE @ MUIR ELEMENTARY/KAMIAKIN MIDDLE	1
KRKF003	EB 80TH ST @ ROSE HILL ELEMENTARY	1
KRKF004	WB 80TH ST @ ROSE HILL ELEMENTARY	1
KRKF005	SB 724 STATE ST @ LAKEVIEW ELEMENTARY SCHOOL	1
KRKF006	WB 10600 NE 68TH ST @ LAKEVIEW ELEMENTARY SCHOOL	1
KRKF007	NB 12637 84TH AVE NE @ SANDBURG ES / FINN HILL MS / THOREAU ES	1
KRKF008	SB 14006 84TH AVE NE @ SANDBURG ES / FINN HILL MS / THOREAU ES	1

The AutoPatrol 3D radar fixed speed safety camera system operates by measuring vehicle speed, as well as position relative to the radar to calculate and differentiate multiple vehicles in the radar beam. The speed of a moving vehicle is measured by Doppler radar. Doppler radar is a generally accepted technology used for measuring speed. The AutoPatrol 3D radar technology is used throughout the US and Europe as well as other countries and is approved by the Swiss national metrology institute- METAS.

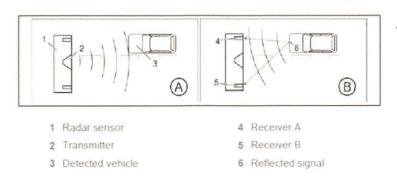
The AutoPatrol 3D radar fixed speed safety camera system uses a tracking radar sensor for measuring vehicle speeds and detecting speed violations. The AutoPatrol 3D radar is aligned at a fixed angle across the road. The AutoPatrol 3D radar emits a horizontal beam over the road surface as represented by the illustration below. The tracking radar can simultaneously detect multiple vehicles and measure their speed, distance, angle and movement within the radar beam. The radar tracks multiple vehicles by reconstructing vehicle movement from the measured object speed, angle and distance values. If a vehicle passes a defined trigger line, the radar

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outputs the vehicle's speed and lane information. The camera connected to the tracking radar uses this information to determine if there is a speed violation and to capture photographs showing the measured speed and lane on the databar of the captured images.



The tracking radar utilizes the Doppler Effect for speed determination. If an electromagnetic wave is emitted at a moving object, then the wave is reflected back from the moving object. The frequency of the wave received back by the radar shifts based on the speed of the moving object and its direction of travel. The tracking radar continuously determines this frequency shift of each object to calculate the object's speed. The tracking radar consists of two receiving antennas integrated into a single radar sensor. This configuration allows the radar to measure the distance and angle of the vehicle relative to the position of the radar sensor. Illustration A and B show the measurement principle in simplified form. The radar sensor emits a radar beam (illustration A). The radar beam is reflected by the vehicle (illustration B). The two receivers receive the reflected radar beam. The radar sensor evaluates the return frequency, as well as the phase difference of the reflected radar beam from both of the receivers. With the aid of these values the radar sensor calculates the vehicle position.



Prior to operation each day, the system performs a system self-test. This self-test performs an electronic tuning fork test to produce a specific frequency and returns an associated speed value. Only if the return value meets the acceptance criteria to show that the system is operating correctly will the system enter measure mode. Unless a self-test is successful, the system will not enter measure mode and no violations will be captured. Additional information stored as metadata within each image includes coordinates of the vehicle position at the time of capture. This information is extracted and utilized through a secondary speed verification process to provide yet another means to validate offender speed and position based on the two images obtained and image analytics. In addition to the internal system checks and the manufacturer calibration certification, the 3D radar system is subject to routine and independent calibration check of the speeds produced by the system at least annually by a qualified technician.

Each day the computer which controls the fixed speed safety camera system is rebooted. The reboot is initiated each day and each time the computer is rebooted an internal check is performed on all operations of

each fixed speed safety camera system, including the clocks, sensors, camera and speed calculating hardware and software, in order to verify that all operations are functioning correctly. When the internal check detects a problem with one of the operations on a given fixed speed safety camera system, then that particular fixed speed safety camera system is inactivated and a request for service is relayed to ATS support personnel. This means that violations cannot be issued until any internal problem is fixed.

Speed validation tests are regularly performed on each installed and operable AutoPatrol 3D radar fixed speed safety camera system. The test is conducted by having a LIDAR Operator obtain true measurements of up to five vehicles per lane in the ascending and/or descending direction. The speed of the vehicle is captured by the LIDAR Operator and then relayed via cellular to an ATS Technician. The ATS Technician then compares the vehicle speed measured by the AutoPatrol 3D radar fixed speed safety camera system to the speed measured by the LIDAR Operator to ensure the accuracy of the AutoPatrol 3D radar fixed speed safety camera system. ATS maintains the results of each test in a Validation Report. The speed validation for each system was performed on the following date and the systems at each location were found to be in proper working order:

Location Code	Location Description	Date of Test
KRKF001	NB 132 nd Ave NE @ Muir Elementary/Kamiakin Middle	5/8/2023
KRKF002	SB 132 nd Ave NE @ Muir Elementary/Kamiakin Middle	5/8/2023
KRKF003	EB 80th St @ Rose Hill Elementary	5/8/2023
KRKF004	WB 80th St @ Rose Hill Elementary	5/8/2023
KRKF005	SB 724 STATE ST @ LAKEVIEW ELEMENTARY SCHOOL	5/8/2023
KRKF006	WB 10600 NE 68TH ST @ LAKEVIEW ELEMENTARY SCHOOL	5/8/2023
KRKF007	NB 12637 84TH AVE NE @ SANDBURG ES / FINN HILL MS / THOREAU ES	5/8/2023
KRKF008	SB 14006 84TH AVE NE @ SANDBURG ES / FINN HILL MS / THOREAU ES	5/8/2023

Preventative maintenance, including visual inspections, is regularly performed on the AutoPatrol 3D radar fixed speed safety camera systems. Preventative maintenance activities include: cleaning of the cameras and housing, general site inspection of environment and road conditions, inspection of poles, bases and enclosures, and inspection of system cables and connections. The location and date that preventative maintenance is performed is recorded in the Preventative Maintenance Log, which along with the Validation Report(s) referenced above, is attached hereto.

I am a custodian, or otherwise qualified witness, as to the attached records. I make this declaration based on personal knowledge, and if called and sworn as a witness, I could and would testify as set forth in the following paragraph.

Attached as Exhibits are: Exhibit A - Speed Validation Reports, Exhibit B - Preventative Maintenance Logs, and Exhibit C - Annual System Verification Certificate for all AutoPatrol 3D radar fixed speed safety camera systems installed and used by the City of Kirkland. All documents and materials included as Exhibit A, Exhibit B and Exhibit C are authentic and are what they purport to be, and accurately describe the matters set forth therein. All such records are business records in that they are: (1) records kept in the ordinary course of business; (2) created at or near the time of the transactions or events reflected therein by, or based on

information from, a person with knowledge of the transaction or events; and (3) kept as part of a regular business activity.

Based upon my education, training, experience, and knowledge of the AutoPatrol 3D radar fixed speed safety camera system, it is my opinion that the system is so designed and constructed as to accurately employ measurement techniques based on a division of distance over time in such a manner that it will give accurate measurements of the speed of motor vehicles.

I, Lesieli Casale, certify (or declare) under penalty of perjury under the laws of the State of Washington that the foregoing is true and correct.

Dated this 2 day of June. 2023 in Mesa, Arizona

Lesieli Casale, Speed Validation Technician

Lesieli Easale



Speed Validation Report Client: Kirkland, WA

FILED

JUN 15 2023 KIRKLAND MUNICIPAL COURT

Validation Date May 8, 2023

- KRKF001 NB 132ND AVE NE @ MUIR ELEMENTARY/KAMIAKIN MIDDLE
 - o Radar Serial Number: 590-113/66806
- KRKF002 SB 132ND AVE NE @ MUIR ELEMENTARY/KAMIAKIN MIDDLE
 - o Radar Serial Number: 590-113/64016
- KRKF003 EB 80TH ST @ ROSE HILL ELEMENTARY
 - Radar Serial Number: 590-113/63652
- KRKF004 WB 80TH ST @ ROSE HILL ELEMENTARY
 - o Radar Serial Number: 590-113/66135
- KRKF005 SB 724 STATE ST @ LAKEVIEW ELEMENTARY SCHOOL
 - Radar Serial Number: 590-113/65719
- KRKF006 WB 10600 NE 68TH ST @ LAKEVIEW ELEMENTARY SCHOOL
 - o Radar Serial Number: 590-113/61782
- KRKF007 NB 12637 84TH AVE NE @ SANDBURG ES / FINN HILL MS / THOREAU ES
 - o Radar Serial Number: 590-113/65071
- KRKF008 SB 14006 84TH AVE NE @ SANDBURG ES / FINN HILL MS / THOREAU ES
 - o Radar Serial Number: 590-113/63287

Equipment:

Pro-Lite Plus Hand held Lidar Serial Number: LP05509

Certification Date: October 27, 2022 Lidar Operator: Charles Goodrich

RLC Operator: Catherine Koselka-Thompson



A speed validation test was conducted for the sites listed above. The Lidar Operator, obtained true measurements of five vehicles per lane in the ascending and/or descending direction. Those speeds were obtained using a Kustom Signals Pro-Lite+ hand held Lidar instrument. The speed of the vehicle is captured by the Lidar Operator and then relayed via cellular to the RLC Technician. The RLC Technician is monitoring the vehicle speed at the Fixed Speed Camera system simultaneously to ensure the accuracy of the system. The speed validation tests performed on the above-listed dates confirmed the accuracy of the Fixed Speed Camera systems at each location.

I, Lesieli Casale, certify that the information contained in this report is true and accurate.

Signed:

Date: June 2, 2023 Mesa, Arizona

American Traffic Solutions Speed Integrity Team

Lesieli Casale



Certificate of Achievement

Speed Integrity Technician Has successfully completed the 16 hour course for

Speed Integrity Technician

This course encompasses all the necessary tasks required to perform the duties as a Speed Integrity Technician. Through this course each participant is required to display the proper competency through written and practical examinations. In addition, this course certifies each participants as a Lidar operator.

Charles Goodrich

March 29, 2016 This Day:

American Traffic Solutions

Police Traffic Laser/Radar Instructor

Traffic Solutions, Inc., 7681 East Gray Road, Scottsdale, AZ 95090

Certificate of Achievement

Speed Integrity Technician

Has successfully completed the course for Speed Inegrity Technician

This course encompasses all the necessary tasks required to perform the duties as a Speed Integrity Technician. Through this course each participant is required to display the proper competencies in Radar and Laser Technology. In addition, this course certifies each participants as a Radar and Lidar operator

Catherine Koselka Presented to:

August 21st, 2019 This Day:

American Traffic Solutions

Tylor Yochim Radar Instructor

RDLD Certificate of Achievement V10

American Traffic Solutions, Inc., 7681 East Gray Road, Scottsdale, AZ 85260

Certificate # VCC-8821-AZ-02



PB Electronics Inc.

248 W Peaceful Ct., Shepherdsville, KY 40165
502 543-7032 www.pbelectronics.com
Factory Authorized Calibration Center for Stalker, MPH, Kustom, and LTI

Certificate of Calibration

Manufacturer: Kustom

Model: ProLite

Serial Number: LP05509

I hereby certify that this Speed Measuring Device has been checked for accuracy and correctness of operation under my supervision. This Speed Measuring Device is certified accurately within +/- 0.5 mph in stationary mode using equipment traceable to National Institute of Standards and technology.

The laser transmitter of this device has been tested and found to be within specified range for Laser Devices as established by the Federal Communications Commission and IACP.

FCC License number PG-18-12552

Technician Signature

PRELECTRONICS
FACTORY Authorized
Service Center

IVIPIT
INDUSTRIES
LAVER?
O TECHNOLOGY

Date: October 27, 2022





SELF-ACCURACY TEST Kustom Signals Pro-Lite+ Lidar Speed Measurement Tool

DATE: May 8, 2023
Start of shift "Self-Diagnostic test" time:10:36 AM
Start of shift Distance check:l00'lidar
End of shift "Self-Diagnostic test" time:11:53 AM
End of shift Distance check:100'
City and State:Kirkland, WA
Lidar Serial Number:LP05509
Certification Date:October 27 th , 2022
OPERATOR:Charles Goodrich
I, Charles Goodrich, certify that the Kustom Signals Pro-Lite+ Lidar speed measurement device was setup, tested, and operated in accordance with the manufactures specifications to include its self-diagnostic check.
Further, I certified that the self-check distance was completed and accurate.
Signature: a
Date: May 8, 2023





		e pood run	dation from	011001		
Date	Date Date			5/8/2023		
Time			11:47 AM			
Site ID				KRKF0	01	
Location			k	(irkland, Was	shington	
Address			NB 132ND AVE NE @ MUIR ELEMENTARY/KAMIAKI			
Posted Speed	Limit			20MPI	H	
Trigger Speed	d Limit			26MPI	Н	
Speed Type				Schoo	ol	
Lidar Technic	Lidar Technician			Charles Go	odrich	
AutoPatrol Te	chnician		Catherine Thompson			
Lidar Serial N	Lidar Serial Number			LP05509		
Radar Serial I	Number		590-113/66806			
Detection Typ	oe .		Autopatrol-Radar			
Measure Mod	e Capture		Yes			
Photo enforce	ement signs	present		Yes		
Pass/ Fail			Pass			
Ascending or	Descending			Descend	ding	
City Lane	Times	Lidar Speeds	AP Speeds	Delta	Comments	
1	11.47.35	22	23	1		
1	11.48.03	26	25	-1		
1	11.48.29	24	23	-1		
1	11.48.33	27	27	0		
1	11.48.35	28	28	0		





		opood run	dation from	511001		
Date			5/8/2023			
Time			11:43 AM			
Site ID			KRKF002			
Location				Kirkland,	WA	
Address			SB 132ND AVE NE @ MUIR ELEMENTARY/KAMIAM			
Posted Speed	d Limit			20MPH	4	
Trigger Spee	d Limit			26MPH	1	
Speed Type				Schoo	ol .	
Lidar Technic	ian		Charles Goodrich			
AutoPatrol Te	chnician		Catherine Thompson			
Lidar Serial N	umber		LP05509			
Radar Serial I	Number		590-113/64016			
Detection Typ	oe .		Autopatrol-Radar			
Measure Mod	e Capture		Yes			
Photo enforc	ement signs	present	Yes			
Pass/ Fail			Pass			
Ascending or	Descending			Descend	ling	
City Lane	Times	Lidar Speeds	AP Speeds	Delta	Comments	
1	11.43.29	28	29	1		
1	11.44.55	24	25	1		
1	11.45.05	28	29	1		
1	11.45.33	25	26	1		
1	11.46.22	25	26	1		





Date				5/8/202	3
Time			10:41 AM		
Site ID			KRKF003		
Location			K	(irkland, Was	hington
Address			EB 80TH S	T@ROSE H	ILL ELEMENTARY
Posted Speed	Limit			20MPH	
Trigger Speed	d Limit			26MPI	ł
Speed Type				Schoo)l
Lidar Technic	ian			Charles Go	odrich
AutoPatrol Te	chnician		Catherine Thompson		
Lidar Serial N	umber		LP05509		
Radar Serial I	Number		590-113/63652		
Detection Typ	e		Autopatrol-Radar		
Measure Mod	e Capture		Yes		
Photo enforce	ement signs	present	Yes		
Pass/ Fail			Pass		
Ascending or	Descending			Descend	ling
City Lane	Times	Lidar Speeds	AP Speeds	Delta	Comments
1	10.41.18	24	24	0	
1	10.41.21	25	25	0	
1	10.42.30	23	24	1	
1	10.43.11	17	17	0	
1	10.43.14	17	17	0	





Date			5/8/2023			
Time			10:41 AM			
Site ID				KRKF0	04	
Location			ŀ	(irkland, Was	shington	
Address			WB 80TH S	T@ROSEH	ILL ELEMENTARY	
Posted Speed	d Limit			20MPI	Н	
Trigger Speed	d Limit			26MPI	1	
Speed Type				Schoo	ol	
Lidar Technic	ian			Charles Go	odrich	
AutoPatrol Te	chnician		Catherine Thompson			
Lidar Serial N	umber		LP05509			
Radar Serial I	Number		590-113/66135			
Detection Typ	oe .		Autopatrol-Radar			
Measure Mod	e Capture		Yes			
Photo enforce	ement signs	present	Yes			
Pass/ Fail			Pass			
Ascending or	Descending		Descending			
City Lane	Times	Lidar Speeds	AP Speeds	Delta	Comments	
1	10.41.22	32	31	-1		
1	10.41.50	19	18	-1		
1	10.41.59	22	22	0		
1	10.43.03	26	25	-1		
1	10.44.31	26	27	1		





Date				5/8/202	23	
Time		STATE OF THE STATE	10:59 AM			
Site ID				KRKF005		
Location			þ	(irkland, Was		
Address			SB 724 STATE ST @ LAKEVIEW ELEMENTARY SCHOOL			
Posted Speed	d Limit			20MP	H	
Trigger Spee	d Limit			26MP	Н	
Speed Type				Schoo	ol	
Lidar Technic	ian			Charles Go	odrich	
AutoPatrol Te	chnician		Catherine Thompson			
Lidar Serial N	umber		LP05509			
Radar Serial I	Number		590-113/65719			
Detection Typ	oe .		Autopatrol-Radar			
Measure Mod	e Capture		Yes			
Photo enforc		present	Yes			
Pass/ Fail			Pass			
Ascending or	Descending			Descend	ding	
City Lane	Times	Lidar Speeds	AP Speeds	Delta	Comments	
1	10.59.02	27	27	0		
1	10.59.41	29	30	1		
1	10.59.45	31	31	0		
1	10.59.48	32	31	-1		
1	11.00.13	30	31	1		





		opood run	addon Work	OHOUL	
Date			5/8/2023		
Time			10:54 AM		
Site ID				KRKF0	06
Location			H	(irkland, Wa	shington
Address			WB 10600 NE 68TH ST @ LAKEVIEW ELEMENTARY SCHOOL		
Posted Spee	d Limit			20MP	Н
Trigger Spee	d Limit			26MP	H
Speed Type				Schoo	ol
Lidar Technic	ian			Charles Go	odrich
AutoPatrol Te	chnician		Catherine Thompson		
Lidar Serial N	umber		LP05509		
Radar Serial	Number		590-113/61782		
Detection Typ	oe e		Autopatrol-Radar		
Measure Mod	le Capture		Yes		
Photo enforc	ement signs	present	Yes		
Pass/ Fail				Pass	j
Ascending or	Descending			Descend	ding
City Lane	Times	Lidar Speeds	AP Speeds	Delta	Comments
1	10.54.58	28	29	1	
1	10.55.19	29	30	1	
1	10.55.21	27	27	0	
1	10.55.30	26	27	1	
1	10.56.08	26	27	1	





Date		No. of the last of	5/8/2023			
Time			11:14 AM			
Site ID				KRKF0	07	
Location			ŀ	(irkland, Was	hington	
Address			NB 12637 84TH AVE NE @ SANDBURG ES / FINN H			
Posted Speed	d Limit			20MPH	d	
Trigger Spee	d Limit			26MPH	1	
Speed Type				Schoo	ı	
Lidar Technic	cian		Charles Goodrich			
AutoPatrol Te	chnician		Catherine Thompson			
Lidar Serial N	lumber		LP05509			
Radar Serial I	Number		590-113/65071			
Detection Typ	oe .		Autopatrol-Radar			
Measure Mod	le Capture		Yes			
Photo enforc	ement signs	present	Yes			
Pass/ Fail			Pass			
Ascending or	Descending			Descend	ing	
City Lane	Times	Lidar Speeds	AP Speeds	Delta	Comments	
1	11.14.16	35	35	0		
1	11.17.49	35	35	0		
1	11.17.53	33	32	-1		
1	11.18.54	25	26	1		
1	11.19.18	18	17	-1		





Date			5/8/2023				
Time			11:22 AM				
Site ID				KRKF0	08		
Location			H	(irkland, Was	hington		
Address			SB 14006 84TH AVE NE @ SANDBURG ES / FINN HIL MS / THOREAU ES				
Posted Speed	d Limit			20MPH	1		
Trigger Spee	d Limit			26MPH	1		
Speed Type				Schoo	l		
Lidar Technic	ian		Charles Goodrich				
AutoPatrol Technician			Catherine Thompson				
Lidar Serial N	umber		LP05509				
Radar Serial I	Number		590-113/63287				
Detection Typ	oe .		Autopatrol-Radar				
Measure Mod	e Capture		Yes				
Photo enforc	ement signs	present	Yes				
Pass/ Fail			Pass				
Ascending or	Descending			Descend	ing		
City Lane	Times	Lidar Speeds	AP Speeds	Delta	Comments		
1	11.22.28	22	23	1			
1	11.24.44	34	34	0			
1	11.24.52	51	51	0			
1	11.26.06	31	30	-1			
1	11.28.04	35	34	-1			



Previously Flom Test Lab
EMI, EMC, RF Testing Experts Since 1963

toil-free: (366) 311-3268 fax: (480) 926-3598

http://www.ComplianceTesting.com info@ComplianceTesting.com

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JUN 15 2023

KIRKLAND

MUNICIPAL COURT

System Verification Test Report

Prepared for: American Traffic Solutions

Model: RRS24F-ST3 (-40 to +70)

Serial Number: 590-113 / 65719

Description: Radar Beam Characteristics

To

Jenoptik Multi-Radar System Verification Procedure Base Frequency Test

Date of Issue: 9-6-2022

On the behalf of the applicant:

American Traffic Solutions 1150 N Alma School Rd Mesa, AZ 85201

Prepared by
Compliance Testing, LLC
1724 S. Nevada Way
Mesa, Arizona 85204
(480) 926-3100 phone / (480) 926-3598 fax
www.compliancetesting.com

Project No: p2280029

Mark Sechrist

Project Test Engineer

Mark Sechrit



Previously Flom Test Lab EMI, EMC, RF Testing Experts Since 1963 toll-free: (866)311-3268 fax: (480)926-3598

http://www.ComplianceTesting.com info@ComplianceTesting.com

Test Results Summary Table

The frequency measurements performed by Compliance Testing, LLC and reported within this report demonstrate that the Jenoptik RRS24F-ST3 radar system has an accuracy of less than or equal to 0.62 mph in the range 6.21 mph to 62.14 mph and an accuracy of 0.62 mph to 1.86 mph in the range of 62.14 mph to 186.41 mph. This is equal to or better than +/- 1 mph accuracy up to 100 mph.

Test Frequency Set 1

Nominal Frequency (GHz)	Measured Frequency (GHz)	Amplitude (dBm)	Frequency Deviation (MHz)	Limit (MHz)	Results
$F_0 = 24.0800$	24.07880	9.3520	1.19 +/- 0.03	+/- 48.2	PASS
F ₁ = 24.0872	24.08600	9.8990	1.25 +/- 0.03	+/- 48.2	PASS
F ₂ = 24.0890	24.08780	10.990	1.19 +/- 0.03	+/- 48.2	PASS
F ₃ = 24.0900	24.08880	11.264	1.20 +/- 0.03	+/- 48.2	PASS

Test Frequency Set 2

Nominal Frequency (GHz)	Measured Frequency (GHz)	Amplitude (dBm)	Frequency Deviation (MHz)	Limit (MHz)	Results
$F_0 = 24.1200$	24.11860	9.3760	1.40 +/- 0.03	+/- 48.2	PASS
F ₁ = 24.1272	24.12580	9.9350	1.44 +/- 0.03	+/- 48.2	PASS
F ₂ = 24.1290	24.12765	10.998	1.35 +/- 0.03	+/- 48.2	PASS
F ₃ = 24.1300	24.12880	11.204	1.20 +/- 0.03	+/- 48.2	PASS

Test Frequency Set 3

Nominal Frequency (GHz)	Measured Frequency (GHz)	Amplitude (dBm)	Frequency Deviation (MHz)	Limit (MHz)	Results
F ₀ = 24.1600	24.15845	8.8840	1.55 +/- 0.03	+/- 48.2	PASS
F ₁ = 24.1672	24.16570	9.6490	1.54 +/- 0.03	+/- 48.2	PASS
F ₂ = 24.1690	24.16740	10.872	1.59 +/- 0.03	+/- 48.2	PASS
F ₃ = 24.1700	24.16845	11.0000	1.55 +/- 0.03	+/- 48.2	PASS



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toll-free: (366) 311-3268 fax: (480) 926-3598

http://www.ComplianceTesting.com info@ComplianceTesting.com

FILED

JUN 15 2023

KIRKLAND

MUNICIPAL COURT

System Verification Test Report

Prepared for: American Traffic Solutions

Model: RRS24F-ST3 (-40 to +70)

Serial Number: 590-113 / 61782

Description: Radar Beam Characteristics

To

Jenoptik Multi-Radar System Verification Procedure Base Frequency Test

Date of Issue: 9-6-2022

On the behalf of the applicant:

American Traffic Solutions 1150 N Alma School Rd Mesa, AZ 85201

Prepared by
Compliance Testing, LLC
1724 S. Nevada Way
Mesa, Arizona 85204
(480) 926-3100 phone / (480) 926-3598 fax
www.compliancetesting.com

Project No: p2280029

Afzal Fazal

Project Test Engineer

zal Forph



Previously Flom Test Lab EMI, EMC, RF Testing Experts Since 1963 toll-free: (866)311-3268 tax; (480)926-3598

http://www.ComplianceTesting.com info@ComplianceTesting.com

Test Results Summary Table

The frequency measurements performed by Compliance Testing, LLC and reported within this report demonstrate that the Jenoptik RRS24F-ST3 radar system has an accuracy of less than or equal to 0.62 mph in the range 6.21 mph to 62.14 mph and an accuracy of 0.62 mph to 1.86 mph in the range of 62.14 mph to 186.41 mph. This is equal to or better than +/- 1 mph accuracy up to 100 mph.

Test Frequency Set 1

Nominal Frequency (GHz)	Measured Frequency (GHz)	Amplitude (dBm)	Frequency Deviation (MHz)	Limit (MHz)	Results
$F_0 = 24.0800$	24.07875	9.0860	1.24 +/- 0.03	+/- 48.2	PASS
F ₁ = 24.0872	24.08595	9.8040	1.30 +/- 0.03	+/- 48.2	PASS
F ₂ = 24.0890	24.08770	11.138	1.29 +/- 0.03	+/- 48.2	PASS
F ₃ = 24.0900	24.08865	11.091	1.34 +/- 0.03	+/- 48.2	PASS

Test Frequency Set 2

Nominal Frequency (GHz)	Measured Frequency (GHz)	Amplitude (dBm)	Frequency Deviation (MHz)	Limit (MHz)	Results
F ₀ = 24.1200	24.11890	9.0270	1.10 +/- 0.03	+/- 48.2	PASS
F ₁ = 24.1272	24.12625	9.4610	1.00 +/- 0.03	+/- 48.2	PASS
F ₂ = 24.1290	24.12795	10.603	1.05 +/- 0.03	+/- 48.2	PASS
F ₃ = 24.1300	24.12890	10.837	1.09 +/- 0.03	+/- 48.2	PASS

Test Frequency Set 3

Nominal Frequency (GHz)	Measured Frequency (GHz)	Amplitude (dBm)	Frequency Deviation (MHz)	Limit (MHz)	Results
$F_0 = 24.1600$	24.15885	8.7120	1.14 +/- 0.03	+/- 48.2	PASS
F ₁ = 24.1672	24.16615	9.3680	1.10 +/- 0.03	+/- 48.2	PASS
F ₂ = 24.1690	24.16790	10.584	1.10 +/- 0.03	+/- 48.2	PASS
F ₃ = 24.1700	24.16890	10.694	1.10 +/- 0.03	+/- 48.2	PASS





PREVENTIVE MAINTENANCE CHECKLIST

Date & Ti	ime: 05/22	2/2023 8	3:15:00
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Site ID: KRKF005

Location: SB 724 STATE ST @ LAKEVIEW ELEMENTARY SCHOOL

Product: AutoPatrol

Technician Name: Charles Goodrich

See Associated Ticket:

ltem	Status	Note/Action (If Status N/A, please specify)
Clean dirt, grime, and graffiti off enclosure and glass.		
1.1. Clean Graffiti.	Pass	
Check physical integrity. Check paint/housing for graffiti and (or) other vandalism.		
1.2. Clean Glass:	Pass	
Clean and inspect all glass and enclosures.		
1.3. Clean Enclosure (Interior):	Pass	
Clear vents/fans of obstruction. Remove dust and dirt by vacuum/wiping.		
1.4. Check Enclosure:	Pass	
If enclosure moved during cleaning, tighten base.		
Perform a general site inspection to include environmental and road conditions.		
2.1. PLP/Loop Loop:		
Check for exposed or cut loop wiring, and epoxy wear and tear.		
2.2. Power & Grounding:	Pass	
Inspect all power and grounding connections.	1	
2.3. Radar:	Pass	
Inspect radar and cables. Visually inspect antenna.		
2.4. WVDs:		
Check for popped out pucks, visible cracks, or other noticeable damage.		
3. Inspect poles, bases, and enclosures		

3.1. Pole: Check sturdiness. Check hurricane collar and confirm screws are tight.	Pass	
3.2. Base: Check for cracks. Ensure bolts (and latch bolt) are tight and secure inside base.	Pass	
3.3. Enclosure: Confirm straps are tight and secure against pole. Tighten if loose.	Pass	
4. Inspect cables and connections.		
4.1. Cables: Check all cables for visible wear or damage.	Pass	
4.2. Connections: Check for exposed wires on pole connecting to radar, camera enclosure, and strobe.	Pass	

5. Take (and attach) photo of enclosure, pole, and photo enforcement sign(s) for presence and damage.

5.1. Enclosure:



5.3. Photo Enforcement Sign(s):



5.2. Pole:





JUN 15 2023

KIRKLAND MUNICIPAL COURT



PREVENTIVE MAINTENANCE CHECKLIST

Date & Time: 05/22/2023 8:11:00	Site ID: KRKF006	Location: WB 10600 NE 68TH ST @	LAKEVIEW ELEMENTARY SCHOOL	
Product: AutoPatrol	Technicia	nn Name: Charles Goodrich	See Associated Ticket:	

ltem .	Status	Note/Action (If Status N/A, please specify)
Clean dirt, grime, and graffiti off enclosure and glass.		
1.1. Clean Graffiti.	Pass	
Check physical integrity. Check paint/housing for graffiti and (or) other vandalism.		
1.2. Clean Glass:	Pass	
Clean and inspect all glass and enclosures.		
1.3. Clean Enclosure (Interior):	Pass	
Clear vents/fans of obstruction. Remove dust and dirt by vacuum/wiping.		
1.4. Check Enclosure:	Pass	
If enclosure moved during cleaning, tighten base.		
Perform a general site inspection to include environmental and road conditions.		
2.1. PLP/Loop Loop:		
Check for exposed or cut loop wiring, and epoxy wear and tear.		
2.2. Power & Grounding:	Pass	
Inspect all power and grounding connections.		
2.3. Radar:	Pass	
Inspect radar and cables. Visually inspect antenna.	n 5.5%	
2.4. WVDs:		w
Check for popped out pucks, visible cracks, or other noticeable damage.		
3. Inspect poles, bases, and enclosures.		

3.1. Pole: Check sturdiness. Check hurricane collar and confirm screws are tight.	Pass
3.2. Base: Check for cracks. Ensure bolts (and latch bolt) are tight and secure inside base.	Pass
3.3. Enclosure: Confirm straps are tight and secure against pole. Tighten if loose.	Pass
4. Inspect cables and connections.	
4.1. Cables: Check all cables for visible wear or damage.	Pass
4.2. Connections: Check for exposed wires on pole connecting to radar, camera enclosure, and strobe.	Pass

5. Take (and attach) photo of enclosure, pole, and photo enforcement sign(s) for presence and damage.

5.1. Enclosure:



5.3. Photo Enforcement Sign(s):



5.2. Pole:

