1

CERTIFICATE CONCERNING DESIGN AND CONSTRUCTION OF ELECTRONIC SPEED MEASURING DEVICES

I, Lesieli Casale, do certify under penalty of the laws of the State of Washington that the following is true and correct:

I have been employed as a technician by American Traffic Solutions for 2 years. I became a speed validation technician on Janurary 12, 2023 and have over 100 hours performing speed validation tests. I am nationally certified as a RADAR and LIDAR operator. The City of Kirkland currently uses the AutoPatrolTM 3D radar fixed speed safety camera system, an electronic speed measuring device provided through a contract with American Traffic Solutions, Inc. ("ATS"). Part of my duties include monitoring regular testing of the AutoPatrol 3D radar fixed speed safety camera systems used by the City of Kirkland.

ATS contracted with the City of Kirkland to provide an Automated Speed Enforcement ("ASE") system designed to record the speed of a vehicle and obtain photographs or other recorded images of the vehicle and the vehicle's registration plate while the vehicle is traveling in excess of speed limits in certain safety zones within posted limits.

	Location Description	Lanes
Code		Monitored
KRKF001	NB 132ND AVE NE @ MUIR ELEMENTARY/KAMIAKIN MIDDLE	1
KRKF002	SB 132ND AVE NE @ MUIR ELEMENTARY/KAMIAKIN MIDDLE	1
KRKF003	EB 80TH ST @ ROSE HILL ELEMENTARY	1
KRKF004	WB 80TH ST @ ROSE HILL ELEMENTARY	1
KRKF005	SB 724 STATE ST @ LAKEVIEW ELEMENTARY SCHOOL	1
KRKF006	WB 10600 NE 68TH ST @ LAKEVIEW ELEMENTARY SCHOOL	1
KRKF007	NB 12637 84TH AVE NE @ SANDBURG ES / FINN HILL MS /	1

The ASE program includes the use of the AutoPatrol 3D radar fixed speed safety camera systems at the following locations within the City of Kirkland:

The AutoPatrol 3D radar fixed speed safety camera system operates by measuring vehicle speed, as well as position relative to the radar to calculate and differentiate multiple vehicles in the radar beam. The speed of a moving vehicle is measured by Doppler radar. Doppler radar is a generally accepted technology used for measuring speed. The AutoPatrol 3D radar technology is used throughout the US and Europe as well as other countries and is approved by the Swiss national metrology institute- METAS.

SB 14006 84TH AVE NE @ SANDBURG ES / FINN HILL MS / THOREAU

THOREAU ES

ES

KRKF008

The AutoPatrol 3D radar fixed speed safety camera system uses a tracking radar sensor for measuring vehicle speeds and detecting speed violations. The AutoPatrol 3D radar is aligned at a fixed angle across the road. The AutoPatrol 3D radar emits a horizontal beam over the road surface as represented by the illustration below. The tracking radar can simultaneously detect multiple vehicles and measure their speed, distance, angle and movement within the radar beam. The radar tracks multiple vehicles by reconstructing vehicle movement from the measured object speed, angle and distance values. If a vehicle passes a defined trigger line, the radar

1 HIS DOCUMENT IS MAINTAINED1AS A PUBLIC RECORD INACCORDANCE WITH RCW 5.44

outputs the vehicle's speed and lane information. The camera connected to the tracking radar uses this information to determine if there is a speed violation and to capture photographs showing the measured speed and lane on the databar of the captured images.



The tracking radar utilizes the Doppler Effect for speed determination. If an electromagnetic wave is emitted at a moving object, then the wave is reflected back from the moving object. The frequency of the wave received back by the radar shifts based on the speed of the moving object and its direction of travel. The tracking radar continuously determines this frequency shift of each object to calculate the object's speed. The tracking radar consists of two receiving antennas integrated into a single radar sensor. This configuration allows the radar to measure the distance and angle of the vehicle relative to the position of the radar sensor. Illustration A and B show the measurement principle in simplified form. The radar sensor emits a radar beam (illustration A). The radar sensor evaluates the return frequency, as well as the phase difference of the reflected radar beam from both of the receivers. With the aid of these values the radar sensor calculates the vehicle position.



Prior to operation each day, the system performs a system self-test. This self-test performs an electronic tuning fork test to produce a specific frequency and returns an associated speed value. Only if the return value meets the acceptance criteria to show that the system is operating correctly will the system enter measure mode. Unless a self-test is successful, the system will not enter measure mode and no violations will be captured. Additional information stored as metadata within each image includes coordinates of the vehicle position at the time of capture. This information is extracted and utilized through a secondary speed verification process to provide yet another means to validate offender speed and position based on the two images obtained and image analytics. In addition to the internal system checks and the manufacturer calibration certification, the 3D radar system is subject to routine and independent calibration check of the speeds produced by the system at least annually by a qualified technician.

Each day the computer which controls the fixed speed safety camera system is rebooted. The reboot is initiated each day and each time the computer is rebooted an internal check is performed on all operations of

each fixed speed safety camera system, including the clocks, sensors, camera and speed calculating hardware and software, in order to verify that all operations are functioning correctly. When the internal check detects a problem with one of the operations on a given fixed speed safety camera system, then that particular fixed speed safety camera system is inactivated and a request for service is relayed to ATS support personnel. This means that violations cannot be issued until any internal problem is fixed.

Speed validation tests are regularly performed on each installed and operable AutoPatrol 3D radar fixed speed safety camera system. The test is conducted by having a LIDAR Operator obtain true measurements of up to five vehicles per lane in the ascending and/or descending direction. The speed of the vehicle is captured by the LIDAR Operator and then relayed via cellular to an ATS Technician. The ATS Technician then compares the vehicle speed measured by the AutoPatrol 3D radar fixed speed safety camera system to the speed measured by the LIDAR Operator to ensure the accuracy of the AutoPatrol 3D radar fixed speed safety camera system. ATS maintains the results of each test in a Validation Report. The speed validation for each system was performed on the following date and the systems at each location were found to be in proper working order:

Location	Location Description	Date of Test
Code		
KRKF001	NB 132 nd Ave NE @ Muir Elementary/Kamiakin Middle	4/20/2023
KRKF002	SB 132 nd Ave NE @ Muir Elementary/Kamiakin Middle	4/20/2023
KRKF003	EB 80 th St @ Rose Hill Elementary	4/20/2023
KRKF004	WB 80 th St @ Rose Hill Elementary	4/20/2023
KRKF005	SB 724 STATE ST @ LAKEVIEW ELEMENTARY SCHOOL	4/24/2023
KRKF006	WB 10600 NE 68TH ST @ LAKEVIEW ELEMENTARY SCHOOL	4/24/2023
KRKF007	NB 12637 84TH AVE NE @ SANDBURG ES / FINN HILL MS / THOREAU ES	4/20/2023
KRKF008	SB 14006 84TH AVE NE @ SANDBURG ES / FINN HILL MS / THOREAU ES	4/20/2023

Preventative maintenance, including visual inspections, is regularly performed on the AutoPatrol 3D radar fixed speed safety camera systems. Preventative maintenance activities include: cleaning of the cameras and housing, general site inspection of environment and road conditions, inspection of poles, bases and enclosures, and inspection of system cables and connections. The location and date that preventative maintenance is performed is recorded in the Preventative Maintenance Log, which along with the Validation Report(s) referenced above, is attached hereto.

I am a custodian, or otherwise qualified witness, as to the attached records. I make this declaration based on personal knowledge, and if called and sworn as a witness, I could and would testify as set forth in the following paragraph.

Attached as Exhibits are: Exhibit A - Speed Validation Reports, Exhibit B - Preventative Maintenance Logs, and Exhibit C - Annual System Verification Certificate for all AutoPatrol 3D radar fixed speed safety camera systems installed and used by the City of Kirkland. All documents and materials included as Exhibit A, Exhibit B and Exhibit C are authentic and are what they purport to be, and accurately describe the matters set forth therein. All such records are business records in that they are: (1) records kept in the ordinary course of business; (2) created at or near the time of the transactions or events reflected therein by, or based on

information from, a person with knowledge of the transaction or events; and (3) kept as part of a regular business activity.

Based upon my education, training, experience, and knowledge of the AutoPatrol 3D radar fixed speed safety camera system, it is my opinion that the system is so designed and constructed as to accurately employ measurement techniques based on a division of distance over time in such a manner that it will give accurate measurements of the speed of motor vehicles.

I, Lesieli Casale, certify (or declare) under penalty of perjury under the laws of the State of Washington that the foregoing is true and correct.

Dated this 10 day of May. 2023 in Mesa, Arizona

Lesieli Casale

Lesieli Casale, Speed Validation Technician



Speed Validation Report Client: Kirkland, WA

Validation Date April 20, 2023

- KRKF001 NB 132ND AVE NE @ MUIR ELEMENTARY/KAMIAKIN MIDDLE
 - o Radar Serial Number: 590-112/66806
- KRKF002 SB 132ND AVE NE @ MUIR ELEMENTARY/KAMIAKIN MIDDLE
 - o Radar Serial Number: 590-112/64016
- KRKF003 EB 80TH ST @ ROSE HILL ELEMENTARY
 - o Radar Serial Number: 590-112/63652
- KRKF004 WB 80TH ST @ ROSE HILL ELEMENTARY
 - o Radar Serial Number: 590-112/65047
- KRKF007 NB 12637 84TH AVE NE @ SANDBURG ES / FINN HILL MS / THOREAU ES
 Radar Serial Number: 590-113/65071
- KRKF008 SB 14006 84TH AVE NE @ SANDBURG ES / FINN HILL MS / THOREAU ES
 - o Radar Serial Number: 590-113/63287

Validation Date April 24, 2023

- KRKF005 SB 724 STATE ST @ LAKEVIEW ELEMENTARY SCHOOL
 - o Radar Serial Number: 590-113/65719
- KRKF006 WB 10600 NE 68TH ST @ LAKEVIEW ELEMENTARY SCHOOL
 - o Radar Serial Number: 590-113/61782

Equipment:

Pro-Lite Plus Hand held Lidar Serial Number: LP05509

- Certification Date: Month Day, Year
- Lidar Operator: Charles Goodrich

Lidar Operator: Tim Usher

RLC Operator: Catherine Koselka-Thompson

RLC Operator: Patricia Hernandez

FILED

MAY 2 5 2023 KIRKLAND MUNICIPALCOURT



A speed validation test was conducted for the sites listed above. The Lidar Operator, obtained true measurements of five vehicles per lane in the ascending and/or descending direction. Those speeds were obtained using a Kustom Signals Pro-Lite+ hand held Lidar instrument. The speed of the vehicle is captured by the Lidar Operator and then relayed via cellular to the RLC Technician. The RLC Technician is monitoring the vehicle speed at the Fixed Speed Camera system simultaneously to ensure the accuracy of the system. The speed validation tests performed on the above-listed dates confirmed the accuracy of the Fixed Speed Camera systems at each location.

I, Lesieli Casale, certify that the information contained in this report is true and accurate.

Lesieli Casale

Signed: _____ Date: May 10, 2023 Mesa, Arizona American Traffic Solutions Speed Integrity Team



Certificate of Ac	hievement
Speed Integrity T Has successfully completed the 16 hour Speed Integrity Technician	course tor
This course encompasses all the necessary tasks required to perfor Technician. Through this course each participant is required to displa written and practical examinations. In addition, this course certifies e	m the duties as a Speed Integrity ay the proper competency through each participants as a Lidar operator.
Presented to: Timothy Usher	
This Day: March 2, 2016	-t-K
American Traffic Solutions	Matthew Giola Police Traffic Laser/Radar festructor
Total an experience of the second s	Descention of the second
Certificate of Ac	hievement
Certificate of Ac <i>Speed Integrity</i> Has successfully completed the 16 hour Speed Integrity Technician	chievement Technician
Certificate of Ac <i>Speed Integrity</i> Has successfully completed the 16 hour Speed Integrity Technician This course encompasses all the necessary tasks required to perfor Technician. Through this course each participant is required to display written and practical examinations. In addition, this course certifies of	Technician r course for m the duties as a Speed Integrity ay the proper competency through each participants as a Lidar operator.
Certificate of Ac <i>Speed Integrity 3</i> Has successfully completed the 16 hour Speed Integrity Technician This course encompasses all the necessary tasks required to be of Speed Integrity Technician This course encompasses all the necessary tasks required to display written and practical examinations. In addition, this course certifies of Marles Goodrich	Technician rourse for m the duties as a Speed Integrity ay the proper competency through each participants as a Lidar operator.
Certificate of Acc <i>Speed Integrity 3</i> Has successfully completed the 16 hour Speed Integrity Technician This course encompasses all the necessary tasks required to perfor Speed Integrity Technician This course encompasses all the necessary tasks required to perfor Speed Integrity Technician Charles Goodrich March 29, 2016	Echnician rourse for m the duties as a Speed Integrity ay the proper competency through each participants as a Lidar operator.

RDLD Centrolis of Antonionant VI-D

American Traffic Solutions, Inc., 7681 East Gray Road, Scottodale, AZ 85260

Cardinate # RDL0-0813 CHI-01



Certificate of Ac	hievement
Speed Integrity Technology Has successfully completed the course for Sp	chnician beed Inegrity Technician
This course encompasses all the necessary tasks required to perfor Through this course each participant is required to display the prope Technology. In addition, this course certifies each participants as a l	m the duties as a Speed Integrity Technician. er competencies in Radar and Laser Lidar operator.
Presented to: Patricia Hernandez	
This Day: January 12, 2023	Typ Vill
RDI D Certificate of Achevement V1.9 American Traffic Solutions. Inc., 7681 East Gray Road.	Tylor Yochim Radar Instructor Scottsdale, AZ 85260 Certificate # VCC-1022-AZ-07
Certificate of Ac	chievement
Speed Integrity Te Has successfully completed the course for s	peed Inegrity Technician
This course encompasses all the necessary tasks required to perform Through this course each participant is required to display the prop Technology. In addition, this course certifies each participants as a	rm the duties as a Speed Integrity Technician. er competencies in Radar and Laser Radar and Lidar operator.
Presented to: Catherine Koselka	
This Day: August 21st, 2019	
American Traffic Solutions	Tyle Yol Tylor Yochim Radar Instructor
RDLD Certificate of Achievement V1.0 American Traffic Solutions, Inc., 7681 East Gray Road	Scottsdale, AZ 85260 Certificate # VCC-0821-AZ-02



	240	PB Electronics Inc.	10/ 10105
	5 5 Factory Authorized	d Calibration Center for Stalker,	s.com MPH, Kustom, and LTI
		Certificate of Calibrati	on
	Manufacturer: Kustom	Model: ProLite	Serial Number: LP05509
he	ereby certify that this Speed eration under my supervision	Measuring Device has been checked . This Speed Measuring Device is c	I for accuracy and correctness of ertified accurately within +/- 0.5 mp
he pe he le	ereby certify that this Speed eration under my supervision stationary mode using equipr e laser transmitter of this dev vices as established by the F C License number PG-18-12	Measuring Device has been checked This Speed Measuring Device is c ment traceable to National Institute of vice has been tested and found to be Federal Communications Commissio 2552 Technician Signature	I for accuracy and correctness of ertified accurately within +/- 0.5 mp f Standards and technology. within specified range for Laser in and IACP.
he pensor	ereby certify that this Speed eration under my supervision stationary mode using equipr e laser transmitter of this dev vices as established by the F C License number PG-18-12 C License number PG-18-12 C License number PG-18-12 C License number PG-18-12 C License number PG-18-12	Measuring Device has been checked This Speed Measuring Device is c ment traceable to National Institute of vice has been tested and found to be Federal Communications Commissio 2552 Technician Signature Date: October 27, 2022	I for accuracy and correctness of ertified accurately within +/- 0.5 mp f Standards and technology. within specified range for Laser in and IACP.





SELF-ACCURACY TEST Kustom Signals Pro-Lite+ Lidar Speed Measurement Tool

DATE: _____4/20/2023_____

Start of shift "Self Diagnostic test" time: _____11:25 AM_____

Start of shift Distance check: ____100'____lidar

End of shift "Self Diagnostic test" time: 1:23 PM

End of shift Distance check: _____100'_____

City and State: ____Kirkland, WA_____

Lidar Serial Number: LP05509

Certification Date: October 27, 2022

OPERATOR: Tim Usher_____

I, *Tim Usher*, certify that the Kustom Signals Pro-Lite+ Lidar speed measurement device was setup, tested, and operated in accordance with the manufactures specifications to include its self-diagnostic check.

Further, I certified that the self-check distance was completed and accurate.

Signature: *Tim Usher*

Date: 4/20/2023



	SELF-ACCURACY TEST
ł	Kustom Signals Pro-Lite+ Lidar Speed Measurement Tool
D	ATE: April 24, 2023
S	tart of shift "Self-Diagnostic test" time:11:19 AM
S	tart of shift Distance check:100'lidar
E	nd of shift "Self-Diagnostic test" time:11:50 AM
E	nd of shift Distance check:100'
С	ity and State:Kirkland, WA
L	idar Serial Number:LP05509
C	Certification Date:October 27th, 2023
0	PERATOR:Charles Goodrich
I, sj a d	<i>Charles Goodrich</i> , certify that the Kustom Signals Pro-Lite+ Lidar peed measurement device was setup, tested, and operated in ccordance with the manufactures specifications to include its self- iagnostic check.
F	urther, I certified that the self-check distance was completed and ccurate.
S D	ignature: Constant Co





the second se						
Date			4/20/2023			
Time			12:18 PM			
Site ID				KRKFO	01	
Location			Ki	rkland, Wa	shington	
Address			NB 1	32ND AVE	NE @ MUIR	
Audress			ELEMEN	TARY/KAN	IAKIN MIDDLE	
Posted Spee	ed Limit			20MP	H	
Trigger Spe	ed Limit	Carlos Comercia de Carlos		26MP	H	
Speed Type				Schoo	ol	
Lidar Techn	ician			Tim Us	her	
AutoPatrol T	echnician		Patricia Hernandez			
Lidar Serial	Number		LP05509			
Radar Serial	Number		590-113/66806			
Detection Ty	/pe			Autopatrol	-Radar	
Measure Mo	de Capture	e		Yes		
Photo enfor	cement sig	ns present		Yes		
Pass/ Fail		and the state of	Pass			
Ascending o	or Descend	ing	Descending			
City Lane	Times	Lidar Speeds	AP Speeds	Delta	Comments	
1	12.18.36	21	22	1		
1	12.19.14	23	22	-1		
1	12.19.29	30	29	-1		
1	12.19.34	26	26	0		
1 12.19.45 24			23 -1			





Date	and the second		4/20/2023			
Time			12:23 PM			
Site ID	Section 1			KRKF	002	
Location	- ALL SALVE			Kirkland	A, WA	
Address			SB 132ND AVE NE @ MUIR			
Posted Spee	ed Limit	The second state of the se		20MF	PH	
Trigger Spe	ed Limit			26MF	PH	
Speed Type		The second second second		Scho	ol	
Lidar Techni	ician			Tim Us	her	
AutoPatrol T	echnician	STATE OF STATE	Patricia Hernandez			
Lidar Serial	Number		LP05509			
Radar Serial	Number	STATE OF STATE	590-113/64016			
Detection T	pe		Autopatrol-Radar			
Measure Mo	de Capture		Yes			
Photo enfor	cement sig	ns present	Yes			
Pass/ Fail			Pass			
Ascending o	or Descend	ing	Descending			
City Lane	Times	Lidar Speeds	AP Speeds	Delta	Comments	
1	12.23.22	26	26	0		
1	12.23.46	34	35	1		
1	12.24.46	32	31	-1	all and the base	
1	12.24.51	28	27	-1		
1	12.24.57	33	32	-1		





Date		No. of the second second	4/20/2023		
Time		The second second	11:40 AM		
Site ID		and the start	KRKF003		
Location	Mar Car als	Contraction P.C.	Ki	rkland, Was	shington
Address			EB 80th	St @ Rose	Hill Elementary
Posted Spee	ed Limit	and the second second		20MP	Н
Trigger Spe	ed Limit			26MP	Н
Speed Type				Schoo	bl
Lidar Techni	cian			Tim Us	ner
AutoPatrol T	echnician		Patricia Hernandez		
Lidar Serial	Number		LP05509 590-113/63652 Autopatrol-Radar Yes Yes Pass		
Radar Serial	Number				
Detection Ty	pe				
Measure Mo	de Capture	e			
Photo enfor	cement sig	ns present			
Pass/ Fail		a service and the service of the ser			
Ascending o	r Descend	ing	Descending		
City Lane	Times	Lidar Speeds	AP Speeds	Delta	Comments
1	11.40.51	26	26	0	
1	11.42.00	27	27	0	
1	11.42.26	26	25	-1	
1	11.42.38	25	26	1	
1	11.42.57	26	25	-1	





Date			4/20/2023		
Time			11:47 AM		
Site ID				KRKF0	04
Location			Ki	rkland, Was	shington
Address		1	WB 80th	St @ Rose	Hill Elementary
Posted Spee	ed Limit			20MP	Н
Trigger Spe	ed Limit			26MP	Н
Speed Type				Schoo	bl
Lidar Techni	cian			Tim Ush	ier
AutoPatrol T	echnician		Patricia Hernandez		
Lidar Serial	Number		LP05509		
Radar Serial	Number		590-113/65047		
Detection Ty	pe	Chest Instantion	Autopatrol-Radar		
Measure Mo	de Capture	9		Yes	
Photo enfor	cement sig	ns present	Yes		
Pass/ Fail			Pass		
Ascending o	r Descend	ing	Descending		
City Lane	Times	Lidar Speeds	AP Speeds	Delta	Comments
1	11.47.02	25	24	-1	
1	11.47.30	22	21	-1	
1	11.48.55	24	23	-1	
1	11.49.56	26	25	-1	
1 11.50.10 19			18 -1		





Date	13-22		4/24/2023		
Time			11:34 AM		
Site ID				KRKF0	05
Location			Ki	rkland, Was	shington
Address			SB 724 STATE	ST@LAKE	VIEW ELEMENTARY
Posted Spee	ed Limit			20MP	Н
Trigger Spe	ed Limit			26MP	н
Speed Type				Schoo	bl
Lidar Techni	ician			Charles Go	odrich
AutoPatrol Technician			C	atherine Th	ompson
Lidar Serial	Number	and the second	LP05509 590-113/65719 Autopatrol-Radar Yes Yes		
Radar Serial	Number				
Detection Ty	pe	a same the			
Measure Mo	de Captur	e			
Photo enfor	cement sig	ns present			
Pass/ Fail				Pass	
Ascending o	r Descend	ing	Descending		
City Lane	Times	Lidar Speeds	AP Speeds	Delta	Comments
1	11.34.07	33	34	1	
1	11.35.20	25	25	0	
1	11.35.26	30	30	0	
1	11.35.27	31	31	0	
1 11.35.29 32			32 0		





Date		R. Laura	4/24/2023		
Time			11:30 AM		
Site ID	N. Ander			KRKFO	006
Location			Ki	rkland, Wa	shington
Address			WB 10600 NE 68TH ST @ LAKEVIEW ELEMENTARY SCHOOL		
Posted Spee	ed Limit			20MP	'n
Trigger Spe	ed Limit			26MP	Υ Η
Speed Type				Scho	ol
Lidar Techni	ician			Charles Go	odrich
AutoPatrol T	echnician		Catherine Thompson		
Lidar Serial	Number	- 2 · 2	LP05509		
Radar Serial	Number		590-113/61782		
Detection Ty	/pe		Autopatrol-Radar		
Measure Mo	de Capture	e		Yes	
Photo enfor	noto enforcement signs present			Yes	
Pass/ Fail			Pass		
Ascending o	or Descend	ing	Descending		
City Lane	Times	Lidar Speeds	AP Speeds	Delta	Comments
1	11.30.50	28	29	1	
1	11.30.55	22	23	1	
1	11.30.58	22	23	1	
1	11.31.20	17	16	-1	
1	11.32.17	25	26	1	



Date			4/20/2023				
Time			12:57 PM				
Site ID			KRKF007				
Location			Ki	rkland, Wa	ashington		
Address			NB 12637 84TH AVE NE @ SANDBURG ES / FINN HILL MS / THOREAU ES				
Posted Spee	ed Limit			20M	РН		
Trigger Spe	ed Limit	A CONTRACTOR OF THE STATE		26M	РН		
Speed Type				Scho	lool		
Lidar Technician			Tim Usher				
AutoPatrol Technician			Patricia Hernandez				
Lidar Serial	Number	24121 112	LP05509				
Radar Serial	Number			590-113/	65071		
Detection Ty	pe			Autopatro	I-Radar		
Measure Mo	de Capture			Yes	5		
Photo enfor	cement sig	ns present	Yes				
Pass/ Fail			Pass				
Ascending o	r Descend	ing	Descending				
City Lane	Times	Lidar Speeds	AP Speeds Delta Comment		Comments		
1	12.57.02	31	31	0			
1	12.58.30	20	21	1			
1	12.59.47	26	27	1			
1	01.01.55	31	30	-1			
1	01.02.53	23	24	1			





Date			4/20/2023				
Time			1:08 PM				
Site ID			KRKF008				
Location			K	irkland, Was	shington		
Address			SB 14006 84TH AVE NE @ SANDBURG ES / FINN HILL MS / THOREAU ES				
Posted Spee	ed Limit	the second second		20MP	Н		
Trigger Spe	ed Limit	and the second		26MP	H		
Speed Type		and the second		Schoo	ol		
Lidar Techni	ician			Tim Ush	ner		
AutoPatrol Technician			Patricia Hernandez				
Lidar Serial	Number		LP05509				
Radar Serial	Number		590-113/63287				
Detection Ty	pe		Autopatrol-Radar				
Measure Mo	de Captur	e	Yes				
Photo enfor	cement sig	ns present	Yes				
Pass/ Fail			Pass				
Ascending o	r Descend	ing	Descending				
City Lane	Times	Lidar Speeds	AP Speeds	Delta	Comments		
1	01.08.04	24	23	-1			
1	01.08.37	28	27	-1			
1	01.09.25	33	32	-1			
1	01.11.02	18	19	1			
1	01.12.04	27	27	0			



Compliance Testing, LLC

Previously Flom Test Lab EMI, EMC, RF Testing Experts Since 1963

> System Verification Test Report

Prepared for: American Traffic Solutions

Model: RRS24F-ST3 (-40 to +70)

Serial Number: 590-113 / 65719

Description: Radar Beam Characteristics

toll-free: (866) 311-3268 fax: (480) 926-3598

http://www.ComplainceTesting.com info@ComplainceTesting.com

> MAY 2 5 7073 KIKKLAND MUNICIPAL COURT

То

Jenoptik Multi-Radar System Verification Procedure Base Frequency Test

Date of Issue: 9-6-2022

On the behalf of the applicant:

American Traffic Solutions 1150 N Alma School Rd Mesa, AZ 85201

Prepared by Compliance Testing, LLC 1724 S. Nevada Way Mesa, Arizona 85204 (480) 926-3100 phone / (480) 926-3598 fax www.compliancetesting.com Project No: p2280029

Mark Sechint

Mark Sechrist Project Test Engineer

THIS DOCUMENT IS MAINTAINED AS A PUBLIC RECORD IN ACCORDANCE WITH RCW 5.44

p2280029-65719_System Verification_Rev 1.0



tol-free: (866) 311-3268 fax: (480) 926-3598

Previously Flom Test Lab EMI, EMC, RF Testing Experts Since 1963

http://www.ComplainceTesting.com info@ComplainceTesting.com

Test Results Summary Table

The frequency measurements performed by Compliance Testing, LLC and reported within this report demonstrate that the Jenoptik RRS24F-ST3 radar system has an accuracy of less than or equal to 0.62 mph in the range 6.21 mph to 62.14 mph and an accuracy of 0.62 mph to 1.86 mph in the range of 62.14 mph to 186.41 mph. This is equal to or better than +/- 1 mph accuracy up to 100 mph.

Test Frequency Set 1

Nominal Frequency (GHz)	Measured Frequency (GHz)	Amplitude (dBm)	Frequency Deviation (MHz)	Limit (MHz)	Results
F ₀ = 24.0800	24.07880	9.3520	1.19 +/- 0.03	+/- 48.2	PASS
F ₁ = 24.0872	24.08600	9.8990	1.25 +/- 0.03	+/- 48.2	PASS
F ₂ = 24.0890	24.08780	10.990	1.19 +/- 0.03	+/- 48.2	PASS
F ₃ = 24.0900	24.08880	11.264	1.20 +/- 0.03	+/- 48.2	PASS

Test Frequency Set 2

Nominal Frequency (GHz)	Measured Frequency (GHz)	Amplitude (dBm)	Frequency Deviation (MHz)	Limit (MHz)	Results
F ₀ = 24.1200	24.11860	9.3760	1.40 +/- 0.03	+/- 48.2	PASS
F ₁ = 24.1272	24.12580	9.9350	1.44 +/- 0.03	+/- 48.2	PASS
F ₂ = 24.1290	24.12765	10.998	1.35 +/- 0.03	+/- 48.2	PASS
F ₃ = 24.1300	24.12880	11.204	1.20 +/- 0.03	+/- 48.2	PASS

Test Frequency Set 3

Nominal Frequency (GHz)	Measured Frequency (GHz)	Amplitude (dBm)	Frequency Deviation (MHz)	Limit (MHz)	Results
F ₀ = 24.1600	24.15845	8.8840	1.55 +/- 0.03	+/- 48.2	PASS
F ₁ = 24.1672	24.16570	9.6490	1.54 +/- 0.03	+/- 48.2	PASS
F ₂ = 24.1690	24.16740	10.872	1.59 +/- 0.03	+/- 48.2	PASS
F ₃ = 24.1700	24.16845	11.0000	1.55 +/- 0.03	+/- 48.2	PASS



Compliance Testing, LLC

Previously Flom Test Lab EMI, EMC, RF Testing Experts Since 1963

System Verification Test Report

Prepared for: American Traffic Solutions

Model: RRS24F-ST3 (-40 to +70)

Serial Number: 590-113 / 61782

Description: Radar Beam Characteristics

То

Jenoptik Multi-Radar System Verification Procedure Base Frequency Test

Date of Issue: 9-6-2022

On the behalf of the applicant:

American Traffic Solutions 1150 N Alma School Rd Mesa, AZ 85201

Prepared by Compliance Testing, LLC 1724 S. Nevada Way Mesa, Arizona 85204 (480) 926-3100 phone / (480) 926-3598 fax www.compliancetesting.com Project No: p2280029

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Afzal Fazal Project Test Engineer

FILED MAY 2.5 2023 KIRKLAND MUNICIPAL COURT

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Test Results Summary Table

The frequency measurements performed by Compliance Testing, LLC and reported within this report demonstrate that the Jenoptik RRS24F-ST3 radar system has an accuracy of less than or equal to 0.62 mph in the range 6.21 mph to 62.14 mph and an accuracy of 0.62 mph to 1.86 mph in the range of 62.14 mph to 186.41 mph. This is equal to or better than +/- 1 mph accuracy up to 100 mph.

Test Frequency Set 1

Nominal Frequency (GHz)	Measured Frequency (GHz)	Amplitude (dBm)	Frequency Deviation (MHz)	Limit (MHz)	Results
F ₀ = 24.0800	24.07875	9.0860	1.24 +/- 0.03	+/- 48.2	PASS
F ₁ = 24.0872	24.08595	9.8040	1.30 +/- 0.03	+/- 48.2	PASS
F ₂ = 24.0890	24.08770	11.138	1.29 +/- 0.03	+/- 48.2	PASS
F ₃ = 24.0900	24.08865	11.091	1.34 +/- 0.03	+/- 48.2	PASS

Test Frequency Set 2

Nominal Frequency (GHz)	Measured Frequency (GHz)	Amplitude (dBm)	Frequency Deviation (MHz)	Limit (MHz)	Results
F ₀ = 24.1200	24.11890	9.0270	1.10 +/- 0.03	+/- 48.2	PASS
F ₁ = 24.1272	24.12625	9.4610	1.00 +/- 0.03	+/- 48.2	PASS
F ₂ = 24.1290	24.12795	10.603	1.05 +/- 0.03	+/- 48.2	PASS
F ₃ = 24.1300	24.12890	10.837	1.09 +/- 0.03	+/- 48.2	PASS

Test Frequency Set 3

Nominal Frequency (GHz)	Measured Frequency (GHz)	Amplitude (dBm)	Frequency Deviation (MHz)	Limit (MHz)	Results
F ₀ = 24.1600	24.15885	8.7120	1.14 +/- 0.03	+/- 48.2	PASS
F ₁ = 24.1672	24.16615	9.3680	1.10 +/- 0.03	+/- 48.2	PASS
F ₂ = 24.1690	24.16790	10.584	1.10 +/- 0.03	+/- 48.2	PASS
F ₃ = 24.1700	24.16890	10.694	1.10 +/- 0.03	+/- 48.2	PASS

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3.1. Pole: Check sturdiness. Check hurricane collar and confirm screws are tight.	Pass	
3.2. Base: Check for cracks. Ensure bolts (and latch bolt) are tight and secure inside base.	Pass	
3.3. Enclosure: Confirm straps are tight and secure against pole. Tighten if loose.	Pass	
4. Inspect cables and connections.		
4.1. Cables: Check all cables for visible wear or damage.	Pass	
4.2. Connections: Check for exposed wires on pole connecting to radar, camera enclosure, and strobe.	Pass	

5. Take (and attach) photo of enclosure, pole, and photo enforcement sign(s) for presence and damage.

5.1. Enclosure:



PHOTO

5.3. Photo Enforcement Sign(s):

5.2. Pole:



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 WERKLAND MUNICIPAL COURT

 PREVENTIVE MAINTENANCE CHECKLIST

 Date & Time: 04/13/2023 8:13:00
 Site ID: KRKF006

 Location: WB 10600 NE 68TH ST @ LAKEVIEW ELEMENTARY SCHOOL

 Product: AutoPatrol
 Technician Name: Charles Goodrich

 Item
 Status

tion	otutuo	HoterHoter (in otatus tark, picase specify)
1. Clean dirt, grime, and graffiti off enclosure and glass.		
1.1. Clean Graffiti.	Pass	
Check physical integrity. Check paint/housing for graffiti and (or) other vandalism.		
1.2. Clean Glass:	Pass	
Clean and inspect all glass and enclosures.		
1.3. Clean Enclosure (Interior):	Pass	
Clear vents/fans of obstruction. Remove dust and dirt by vacuum/wiping.		
1.4. Check Enclosure:	Pass	
If enclosure moved during cleaning, tighten base.		
2. Perform a general site inspection to include environmental and road conditions.		
2.1. PLP/Loop Loop:		
Check for exposed or cut loop wiring, and epoxy wear and tear.		
2.2. Power & Grounding:	Pass	
Inspect all power and grounding connections.		
2.3. Radar:	Pass	
Inspect radar and cables. Visually inspect antenna.		
2.4. WVDs:		
Check for popped out pucks, visible cracks, or other noticeable damage.		
3. Inspect poles, bases, and enclosures.		

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Pass	
Pass	
Pass	
Pass	
Pass	
	Pass Pass Pass Pass Pass

5. Take (and attach) photo of enclosure, pole, and photo enforcement sign(s) for presence and damage.

5.1. Enclosure:



5.2. Pole:

-



5.3. Photo Enforcement Sign(s):